

Statistical Learning with Extreme Values Master MVA
École Normale Supérieure Paris-Saclay

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Validation rules: see syllabus

50% homework: each course comes with a list of exercises, partly coding, partly theory. These exercises should be handed out 2 weeks maximum after the day they are released. There is a bonus rule allowing students to improve upon past exercises (maximum 4 of them after a Q&A last course).

50% oral presentation (20 minutes, 10 slides) + written report (≤ 10 pages)

Course structure: each session is approximately divided into a 2h lecture and a 1h tutorial.

Chapter 1

Fundamentals of Extreme Value Analysis: learning from block maxima

- Course material for this chapter: [Resnick \(1987\)](#), chapters 0.1–0.3 (very concise); [Leadbetter et al. \(2012\)](#) (very detailed and easy to read), [De Haan and Ferreira \(2007\)](#), chapter 1 (additional results, more advanced).
- Other readings : [Beirlant et al. \(2004\)](#) (chapter 1) or [Resnick \(2007\)](#) Chapter 1 : examples of case studies and exploratory data analysis ; [Coles \(2001\)](#), chapters 3, 4: classical statistical methods.

1.1 Extreme Value Theory: what and why ?

1.1.1 Context, motivations

Extreme value theory (EVT) relies on elegant probability theory and finds natural statistical applications in many fields related to risk management (insurance, finance, telecommunication, climate, environmental sciences. . .).

To fix ideas (see Figure 1.1.1), call X our quantity of interest (X is a real valued random variable), which may be *e.g.* the water level on a coastal point, temperature, insurance claims . . . say we observe *i.i.d.* realizations $X_t, 1 \leq t \leq n$. Some questions of interest for risk management are

- Given a high threshold u , find $p = \mathbb{P}(X \geq p)$
- Given p (e.g. $p = 10^{-4}$), find u such that $\mathbb{P}(X > u) \leq p$.
- Given a long duration T (e.g. 10^4), and a high threshold u , find $p = \mathbb{P}(\max_{t \leq T} X_t \leq u)$.

In probabilistic terms, this is about estimating high quantiles or small probabilities. Unfortunately, it may happen that the sample size is too small for the naive empirical estimators to be of interest. As an example, if u is outside the range of observed data,

$$\hat{p}_n = \frac{1}{n} \sum_t \mathbb{1}_{x_t > u} = 0.$$

Another example about quantiles: we adopt throughout this course the following definition of the *quantile function*:

$$Q(p) = \inf\{x \in \mathbb{R} : F(x) \geq p\} \quad (1.1)$$

where F is the distribution function of the r.v. X under consideration.

An empirical counterpart of (1.1) based on n *i.i.d.* data is

$$\begin{aligned} \hat{Q}_n(p) &= \inf\{x \in \mathbb{R} : \hat{F}_n(x) \geq p\} = \inf\{x : \sum \mathbb{1}_{X_i \leq x} \geq np\} \\ &= X_{(\lceil np \rceil)}, \end{aligned}$$

where $X_{(1)} \leq X_{(2)} \leq \dots \leq X_{(n)}$ are the order statistics of the sample $(X_t)_{1 \leq t \leq n}$. If one is interested in a very high quantile $Q(p)$ (*i.e.* p close to one) such that $1 > p > 1 - 1/n$, then $\lceil np \rceil = n$ and $\hat{Q}_n(p) = X_{(n)}$. There is no hope to estimate correctly such a quantile in a purely empirical manner.

To estimate such extremal quantities based on moderate sample sizes, one need additional assumption to be able to *extrapolate*, *e.g.* from what is observed above moderately high thresholds (left panel of Figure 1.1.1). As we shall see later on, it turns out that the answer to those questions depends on the (asymptotic) distribution of the *maximum* of n *i.i.d.* realizations of X , when n is large.

Annual maximum of seal level at Port Pirie

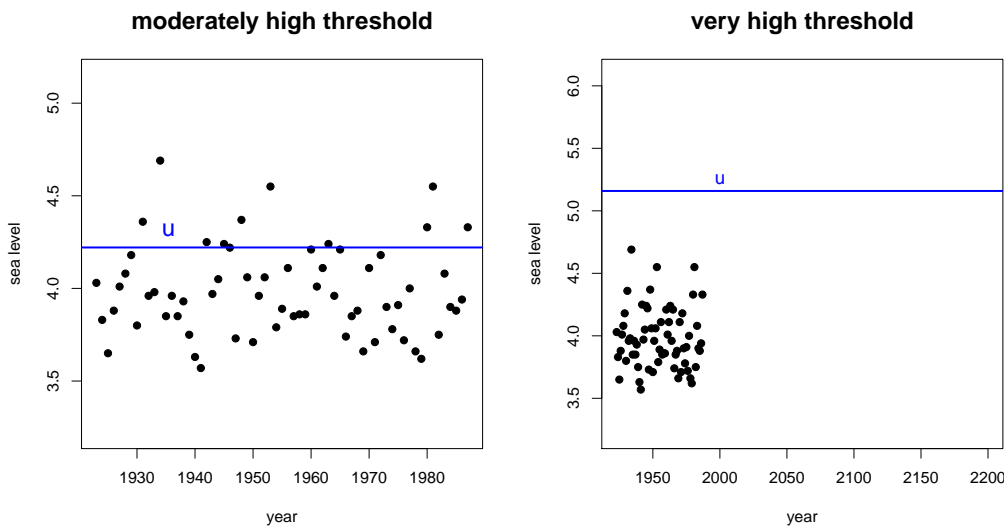


Figure 1.1: Why the empirical measure is not always useful as it is

Notations the maximum operator is denoted by \bigvee , so that for real numbers $x_i, 1 \leq i \leq n$, $\bigvee_{i=1}^n x_i = \max_{i=1}^n x_i$. Similarly, \bigwedge is the minimum operator. In the multivariate case, these operators are understood componentwise, *i.e.* if $x_i = (x_{i,1}, \dots, x_{i,d})$,

$$\bigvee_{i=1}^n x_i = (\bigvee_{i=1}^n x_{i,1}, \dots, \bigvee_{i=1}^n x_{i,d})$$

1.1.2 Rationale behind Extreme value theory (EVT)

The general purpose of EVT is to find statistical models for “extremes” (defined as maxima or excesses above large thresholds), supported by the theory (together with estimation tools). Consider *i.i.d.* copies X_i ($i \in \mathbb{N}$) of a random variable / vector / process X . Let us denote by $[X \mid \|X\| > u]$ the conditional distribution of X on the event $\{\|X\| > u\}$. Then under minimal assumptions,

$$\bigvee_{i=1}^n X_i \quad \text{and} \quad [X \mid \|X\| > u]$$

both converge to a certain class (as $n \rightarrow \infty$ or $u \rightarrow \infty$), up to a suitable normalization. Convergence of maxima is understood in the weak sense (convergence in distribution). Of course, convergence of the conditional distribution $[X \mid \|X\| > u]$ is also a convergence in distribution. Interestingly enough, convergence of the maxima is *equivalent* to convergence of the conditional distribution of excesses. The main idea of extreme value analysis is to use the class of possible limits as a model for the law of the maximum over a long period of interest (the duration of a contract, the next 100 years for a dam, the next 1000 years for a nuclear plant, ...) or for the distribution of ‘large’ values (above a sufficiently high threshold). Inference in the appropriate model will be performed using the few (say k) largest data from a dataset of size n . Convergence of the various estimators is generally obtained under the assumption that $n \rightarrow \infty$, $k = k(n) \rightarrow \infty$, but k is a ‘small proportion’ of n , *i.e.* $k = o(n)$.

Why do we need renormalization? If F is the cumulative distribution function (*c.d.f.*) of X and if the X_i ’s are *i.i.d.*, then the *c.d.f.* for $M_n := \bigvee_{i=1}^n X_i$ is

$$F_n(x) = \mathbb{P}(M_n \leq x) = \mathbb{P}(\forall i \leq n, X_i \leq x) = F(x)^n.$$

Thus, if we do not ‘normalize’ the maximum, its distribution F_n is such that $F_n(x) \rightarrow 0$ as soon as $F(x) < 1$ and the limit distribution function (if there is one) is degenerate. Similarly, the distribution of X , given that $\|X\| \geq u$ ‘escapes’ to infinity.

1.1.3 A CLT for maxima ?

Recall that the Central Limit Theorem states that, if X has finite second moment, we have

$$\frac{\sum_{i=1}^n X_i - b_n}{a_n} \xrightarrow{w} Z$$

where \xrightarrow{w} stands for convergence in distribution, with Z a centered Gaussian distribution, $b_n = n\mathbb{E}(X)$ and $a_n = \sqrt{n}$.

In extreme value theory, the focus is on the maximum rather than the mean. The working hypothesis is the so-called *maximum-domain of attraction condition* (MDA):

There exist two sequences $(a_n)_{n \geq 0}$, $(b_n)_{n \geq 0}$ of real numbers, with $a_n > 0 \forall n$, and a non-degenerate random variable Z , such that

$$\frac{\bigvee_{i=1}^n X_i - b_n}{a_n} \xrightarrow{w} Z \tag{MDA}$$

where $(X_i)_i$ are *i.i.d.* random variables distributed as X .

Remark 1.1.1 ('non-degenerate'). A random variable is called 'non-degenerate' if its distribution is not concentrated at a single point. In other terms, it means that its c.d.f. F is such that $\exists x < y \in \mathbb{R} : F(x) < F(y) < 1$.

In terms of distribution functions, the (MDA) is equivalent to the existence of a non-degenerate distribution function G such that

$$F^n(a_n x + b_n) \xrightarrow[n \rightarrow \infty]{} G(x) \quad (\text{MDA}')$$

at each point x which is a continuity point of the limit G . If (MDA) (or alternatively (MDA')) holds, X (or F) is said to belong to the *maximum domain of attraction* of Z (or G).

Definition 1.1.2 (Extreme Value Distribution). A non-degenerate distribution function G is called an extreme value distribution if (MDA') is satisfied for some distribution function F and some sequences $a_n > 0, b_n$.

Some natural questions are

- Under which conditions on F do we have (MDA') for some c.d.f. G ?
- What are the possible forms of the limit G ?
- How can we choose the sequences a_n, b_n ?
- What is the relation between (MDA) and the convergence of the conditional distribution of excesses above large thresholds ?

The aim of this chapter (and the next one) is to bring some answers, in the case where X is a real-valued random variable. The multivariate case will be the subject of the last chapter. This course does not cover the case where X is a (continuous) stochastic process.

1.2 Intermediate results

1.2.1 Monotone functions and weak convergence

It is a standard fact that convergence in distribution for random variables is the same as convergence of the associated distribution functions at each continuity point of the limit. In EVT, it is useful to extend this type of convergence to the whole class of monotone functions, as follows.

Definition 1.2.1 (Weak convergence of monotone functions). Let $(H_n)_{n \in \mathbb{N}}$ be a family of monotone functions $\mathbb{R} \rightarrow [-\infty, \infty]$. The functions H_n are said to converge weakly, and we write $H_n \xrightarrow{w} H$, if there exists a monotone function $H : \mathbb{R} \rightarrow [-\infty, \infty]$ such that

$$\forall x \in \mathcal{C}(H), \quad H_n(x) \xrightarrow[n \rightarrow \infty]{} H(x).$$

where $\mathcal{C}(H)$ is the set of continuity points of H , that is

$$\mathcal{C}(H) = \{x \in \mathbb{R} : H(x) \in \mathbb{R} \text{ and } H \text{ is continuous at } x. \}$$

With this definition, if $(X_n)_{n \geq 0}$ and X are random variables with associated distribution functions $(F_n)_{n \geq 0}$ and F , then we indeed have

$$X_n \xrightarrow{w} X \iff F_n \xrightarrow{w} F \quad \text{as } n \rightarrow \infty.$$

Notations When compositions of functions with affine scalings (or with other simple transformations) are involved, *e.g.* if we consider functions of the kind $x \mapsto F(ax + b)$, we will usually use the notation ‘ $F(a \bullet + b)$ ’ instead. As an example,

$$F_n(a_n \bullet + b_n) \xrightarrow{w} G, \quad (n \rightarrow \infty)$$

means

$$\{x \mapsto F_n(a_n x + b_n)\} \xrightarrow{w} G \quad (n \rightarrow \infty).$$

1.2.2 Weak convergence of the inverse

Definition 1.2.2 (Left-continuous inverse). *Let H be a non-decreasing, right continuous function $\mathbb{R} \rightarrow [-\infty, \infty]$. The left-continuous inverse of H is the function*

$$\begin{aligned} H^{\leftarrow} : \mathbb{R} &\rightarrow [-\infty, \infty] \\ y &\mapsto H^{\leftarrow}(y) = \inf\{x \in \mathbb{R} : H(x) \geq y\}, \end{aligned}$$

with the convention that $\inf \mathbb{R} = -\infty$ and $\inf \emptyset = +\infty$.

Remark 1.2.3. *It is left as an exercise to verify that H^{\leftarrow} is indeed continuous from the left.*

Lemma 1.2.4 (Order relations)

Let $H : \mathbb{R} \rightarrow [-\infty, \infty]$ be a non-decreasing, right-continuous function, and let $x \in \mathbb{R}$ and $y \in \mathbb{R}$. Define $A_y = \{t \in \mathbb{R} : H(t) \geq y\}$.

Then A_y is a closed set, and

$$H(x) \geq y \iff x \geq H^{\leftarrow}(y). \tag{1.2}$$

Proof. Notice first that A_y must be either the empty set, or \mathbb{R} , or of the form (u, ∞) or $[u, \infty)$, for some $u \in \mathbb{R}$.

1. If $A_y = \mathbb{R}$, A_y is obviously closed, and $H^{\leftarrow}(y) = -\infty$. Then both sides of (1.2) hold for any $x \in \mathbb{R}$.
2. if $A_y = \emptyset$, A_y is closed again, and $H^{\leftarrow}(y) = +\infty$. Also, $\forall t \in \mathbb{R}, H(t) < y$, thus neither side of (1.2) can be true.
3. Otherwise, consider a sequence $u_n \downarrow u$. Each u_n belongs to A_y , thus $H(u_n) \geq y$. Since H is continuous from the right, $H(u) \geq y$ too, whence $u \in A_y$. Thus $A_y = [u, \infty)$ is closed in \mathbb{R} . By definition of H^{\leftarrow} , we have $H^{\leftarrow}(y) = \inf A_y = u$. Finally, (1.2) is obtained by noticing that

$$H(x) \geq y \iff x \in A_y \iff x \in [H^{\leftarrow}(y), \infty) \iff x \geq H^{\leftarrow}(y)$$

■

Lemma 1.2.5 (Weak convergence of the inverse)

Let $(H_n)_{n \in \mathbb{N}}$ and H be monotone functions $\mathbb{R} \rightarrow [-\infty, \infty]$. If

$$H_n \xrightarrow{w} H \quad \text{as } n \rightarrow \infty,$$

then also

$$H_n^{\leftarrow} \xrightarrow{w} H^{\leftarrow} \quad \text{as } n \rightarrow \infty.$$

Conversely, if we assume in addition that

(i) For all $n \in \mathbb{N}$, $\inf_{\mathbb{R}} H_n \geq \inf_{\mathbb{R}} H$,

(ii) For all $x \in \mathbb{R}$ such that $H(x) < \infty$, $H(x) < \sup_{t: H(t) < \infty} H(t)$,

Then weak convergence of H_n^{\leftarrow} to H^{\leftarrow} implies weak convergence of H_n to H .

The proof is deferred to Appendix A.2 Notice that the two conditions (i) and (ii) for the converse statement of Lemma 1.2.5 may seem intricate, but they are indeed satisfied in the particular case where we need it (*i.e.* in the proof of Theorem 2.1.1).

1.2.3 Convergence to types

The limiting form in (MDA') will be obtained 'up to rescaling', in the sense defined below.

Definition 1.2.6 (Functions of the same type). *Two functions $U, V : \mathbb{R} \rightarrow [-\infty, \infty]$ are of the same type if $\exists A, B \in \mathbb{R}$, $A > 0$, such that*

$$\forall x \in \mathbb{R}, \quad V(x) = U(Ax + B).$$

The interesting fact about equality in type is that, if (MDA) or (MDA') holds for two different sequences, then the limits must be of the same type and the tails of the two sequences must be linked in the same way, as made precise below.

Lemma 1.2.7 (Convergence to types, Khintchine)

Let $(F_n)_n, U$ be cumulative distribution functions, U being non-degenerate. Let $a_n > 0$ and b_n ($n \in \mathbb{N}$) be two sequences of real numbers, such that

$$F_n(a_n \cdot + b_n) \xrightarrow{w} U. \quad (1.3)$$

Let $\tilde{a}_n > 0, \tilde{b}_n$ ($n \in \mathbb{N}$) be two other sequences. Then, the following are equivalent:

(i) There exists another non-degenerate c.d.f. V such that

$$F_n(\tilde{a}_n \cdot + \tilde{b}_n) \xrightarrow{w} V$$

(ii) $\exists A > 0, B \in \mathbb{R}$ such that

$$\frac{\tilde{a}_n}{a_n} \xrightarrow[n \rightarrow \infty]{} A \quad ; \quad \frac{\tilde{b}_n - b_n}{a_n} \xrightarrow[n \rightarrow \infty]{} B.$$

Also, if (i) or (ii) hold, then U and V are of the same type, namely

$$V(\cdot) = U(A \cdot + b) \quad (x \in \mathbb{R}). \quad (1.4)$$

Proof.

1. (i) \Rightarrow (ii) and (1.4):

Assume that (i) holds. Using Lemma 1.2.5, weak convergences in (i) and (1.3) may be inverted, so that

$$\frac{F_n^{\leftarrow} - b_n}{a_n} \xrightarrow{w} U^{\leftarrow} \quad \text{and} \quad \frac{F_n^{\leftarrow} - \tilde{b}_n}{\tilde{a}_n} \xrightarrow{w} V^{\leftarrow}$$

Non-degeneracy allows to pick $y_1 < y_2 \in \mathcal{C}(U^\leftarrow) \cap \mathcal{C}(V^\leftarrow)$ such that $U^\leftarrow(y_1) < U^\leftarrow(y_2)$ and $V^\leftarrow(y_1) < V^\leftarrow(y_2)$. Thus $\frac{F_n^\leftarrow(y_i) - b_n}{a_n} \xrightarrow{w} U^\leftarrow(y_i)$, $i = 1, 2$. By subtraction,

$$\frac{F_n^\leftarrow(y_2) - F_n^\leftarrow(y_1)}{a_n} \xrightarrow{w} U^\leftarrow(y_2) - U^\leftarrow(y_1).$$

In the same way, we have

$$\frac{F_n^\leftarrow(y_2) - F_n^\leftarrow(y_1)}{\tilde{a}_n} \xrightarrow{w} V^\leftarrow(y_2) - V^\leftarrow(y_1).$$

Dividing the two (which is possible since the limits are nonzero) yields

$$\frac{\tilde{a}_n}{a_n} \xrightarrow{n \rightarrow \infty} A := \frac{U^\leftarrow(y_2) - U^\leftarrow(y_1)}{V^\leftarrow(y_2) - V^\leftarrow(y_1)} > 0.$$

Also for $y \in \mathcal{C}(U^\leftarrow) \cap \mathcal{C}(V^\leftarrow)$,

$$\frac{F_n^\leftarrow(y) - b_n}{a_n} - A \frac{F_n^\leftarrow(y) - \tilde{b}_n}{\tilde{a}_n} \xrightarrow{w} U^\leftarrow(y) - AV^\leftarrow(y).$$

However,

$$\begin{aligned} \frac{F_n^\leftarrow(y) - b_n}{a_n} - A \frac{F_n^\leftarrow(y) - \tilde{b}_n}{\tilde{a}_n} &= \frac{F_n^\leftarrow(y) - b_n}{a_n} - A \frac{a_n}{\tilde{a}_n} \frac{F_n^\leftarrow(y) - \tilde{b}_n}{a_n} \\ &\sim_{n \rightarrow \infty} \frac{F_n^\leftarrow(y) - b_n}{a_n} - \frac{F_n^\leftarrow(y) - \tilde{b}_n}{a_n} \\ &= \frac{\tilde{b}_n - b_n}{a_n} \end{aligned}$$

whence $\frac{\tilde{b}_n - b_n}{a_n} \rightarrow B := U^\leftarrow(y) - AV^\leftarrow(y)$; and (ii) is proved.

Another consequence is that the function $y \mapsto U^\leftarrow(y) - AV^\leftarrow(y)$ is identically equal to B on $\mathcal{C}(V^\leftarrow) \cap \mathcal{C}(U^\leftarrow)$, so that $V^\leftarrow(y) = \frac{U^\leftarrow(y) - B}{A} = U[A \cdot + B]^\leftarrow$. By continuity from the left this identity holds everywhere on \mathbb{R} . We obtain

$$V^\leftarrow = [U(A \cdot + B)]^\leftarrow. \quad (1.5)$$

In order to conclude that $V = U(A \cdot + B)$, we need to show that, for two non decreasing functions G_1, G_2 such that $G_1^\leftarrow = G_2^\leftarrow$, it holds that $G_1 = G_2$. To see this, write for $x \in \mathbb{R}$,

$$\begin{aligned} G_1(x) &= \sup\{y : G_1(x) \geq y\} \\ &= \sup\{y : x \geq G_1^\leftarrow(y)\} \quad \text{from Lemma 1.2.4} \\ &= \sup\{y : x \geq G_2^\leftarrow(y)\} \\ &= G_2(x). \end{aligned}$$

2. (ii) \Rightarrow (i) and (1.4): Put $V(x) = U(Ax + B)$, $x \in \mathbb{R}$. Then $V^\leftarrow(y) = A^{-1}(U^\leftarrow(y) - B)$, $y \in \mathbb{R}$. Reversing the argument leading to (1.5), we obtain, for $y \in \mathcal{C}(U^\leftarrow) = \mathcal{C}(V^\leftarrow)$,

$$\begin{aligned} F_n(\tilde{a}_n \cdot + \tilde{b}_n)^\leftarrow(y) &= \frac{F_n^\leftarrow(y) - \tilde{b}_n}{\tilde{a}_n} = \frac{a_n}{\tilde{a}_n} \left(\frac{F_n^\leftarrow(y) - b_n}{a_n} - \frac{(\tilde{b}_n - b_n)}{a_n} \right) \\ &\xrightarrow{n \rightarrow \infty} A^{-1}(U^\leftarrow(y) - B) = V^\leftarrow(y). \end{aligned} \quad (1.6)$$

We have shown that $F_n(\tilde{a}_n \cdot + \tilde{b}_n)^{\leftarrow} \xrightarrow{w} V^{\leftarrow}$, which implies, by Lemma 1.2.5, that $F_n(\tilde{a}_n \cdot + \tilde{b}_n) \xrightarrow{w} V$, which is (i).

Since we have already proved that (i) forces $V(x) = U(Ax + B)$, the proof is complete. ■

1.3 ‘Fundamental theorem’ of EVT: Limit laws for maxima

1.3.1 Max-stable distributions

Getting back to our analogy with the CLT, remind that the limiting distribution \mathcal{N} of rescaled sums (a Gaussian distribution) is *stable*, that is, if $X_i \stackrel{i.i.d.}{\sim} \mathcal{N}$, then for $n \in \mathbb{N}$, $\exists A_n, B_n$: $\frac{\sum_{i=1}^n X_i - B_n}{A_n} \stackrel{d}{=} X_1$. Here and thereafter, ‘ $\stackrel{d}{=}$ ’ means equality *in distribution*.

Replacing the sum-operator by the max-operator, one may reasonably expect an analogous property for extreme value distributions (*i.e.* the limit distributions G in (MDA’)). It is indeed the case, if one consider *max-stability* instead of *stability*, as defined below.

Definition 1.3.1 (Max-stable distribution). *A c.d.f. G is called max-stable if there exist functions $\alpha(t) > 0, \beta(t)$ ($t > 0$) such that*

$$\forall t > 0, \forall x \in \mathbb{R}, \quad G^t(\alpha(t)x + \beta(t)) = G(x).$$

In particular, if $(Z_i)_{i=1, \dots, n} \stackrel{i.i.d.}{\sim} G$, then $\bigvee_{i=1}^n Z_i \sim G^n$, so that, letting $\alpha_n = \alpha(n), \beta_n = \beta(n)$,

$$\frac{\bigvee_{i=1:n} Z_i - \beta_n}{\alpha_n} \stackrel{d}{=} Z_1.$$

Proposition 1.3.2 (Max-stable and extreme value distributions are the same)

Let G be a non-degenerate cumulative distribution function. Then G is an extreme value distribution if and only if it is max-stable.

Proof. If G is max-stable, it is obviously an extreme value distribution: (MDA’) holds with $a_n = \alpha(n), b_n = \beta(n)$.

Conversely, assume that (MDA’) holds for some F and sequences $a_n > 0, b_n$. Fix $t > 0$.

On the one hand, for $x \in \mathcal{C}(G)$,

$$F^{\lfloor nt \rfloor}(a_{\lfloor nt \rfloor}x + b_{\lfloor nt \rfloor}) \xrightarrow{n \rightarrow \infty} G(x). \quad (1.7)$$

Also,

$$F^{\lfloor nt \rfloor}(a_n x + b_n) = (F^n(a_n x + b_n))^{\frac{\lfloor nt \rfloor}{n}} \xrightarrow{n \rightarrow \infty} G^t(x). \quad (1.8)$$

Using Khintchine Lemma 1.2.7, with $F_n = F^{nt}, U = G^t, V = G$ (note that G^t is necessarily a non-degenerate *c.d.f.* if G is so), there exist two real numbers $\alpha(t) > 0, \beta(t)$, such that

$$\frac{a_{\lfloor nt \rfloor}}{a_n} \xrightarrow{n \rightarrow \infty} \alpha(t); \quad \frac{b_{\lfloor nt \rfloor} - b_n}{a_n} \xrightarrow{n \rightarrow \infty} \beta(t) \quad (1.9)$$

and

$$G(x) = G^t(\alpha(t)x + \beta(t)), \quad x \in \mathbb{R}.$$

■

Lemma 1.3.3

The functions $t \mapsto \alpha(t) > 0$ and $t \mapsto \beta(t)$ in the definition of a max-stable distribution are uniquely determined by G , and are Borel-measurable.

Proof.

(1) To show that α and β are unique, it is enough to show that if a non degenerate *c.d.f.* G satisfies

$$G(x) = G(ax + b), \quad x \in \mathbb{R},$$

for some $a > 0, b \in \mathbb{R}$, then necessarily $a = 1, b = 0$. Define $T : x \mapsto ax + b$. The assumption rewrites $G = G \circ T$. Thus, $G = G \circ T^n$, for $n \in \mathbb{N}$. Thus, for $x \in \mathbb{R}$, $G(x) = \lim_n G(T^n x)$. It is then easy to see (exercise 1.1) that if $a \neq 1$, G must be degenerate, and then that b must be null.

(2) The argument leading to (1.9) in the proof of Proposition 1.3.2, with F replaced with G , shows that for $t > 0$,

$$\frac{\alpha(\lfloor nt \rfloor)}{\alpha(n)} \xrightarrow{n \rightarrow \infty} \alpha(t); \quad \frac{\beta(\lfloor nt \rfloor) - \beta(n)}{\alpha(n)} \xrightarrow{n \rightarrow \infty} \beta(t) \tag{1.10}$$

Now the functions $t \mapsto \frac{\alpha(n)}{\alpha(\lfloor nt \rfloor)}$ and $t \mapsto \frac{\beta(n) - \beta(\lfloor nt \rfloor)}{\alpha(\lfloor nt \rfloor)}$ are certainly measurable (they are piecewise constant). Since the pointwise limits of measurable functions are measurable, α and β are measurable. ■

Exercise 1.1:

Complete the proof of Lemma 1.3.3 (1): use the fact that for $x \in \mathbb{R}$, the sequence $(T^n x)_n$ is arithmetico-geometric.

The next paragraph is the core of this chapter

1.3.2 Characterizing max-stable distribution

Before stating the result, notice that characterizing max-stable distributions is the same as characterizing extreme value distributions (the possible limits in (MDA)'), according to Proposition 1.3.2.

Theorem 1.3.4 (Extreme value theorem (Fisher & Tipett 1928, Gnedenko 1943))

If G is a max-stable distribution, G is of one of the three types

$$(i) \text{ Fréchet : } \Phi_\alpha(x) = \begin{cases} e^{-x^{(-\alpha)}} & (x > 0) \\ 0 & (x \leq 0). \end{cases}'$$

With $\alpha > 0$;

$$(ii) \text{ Weibull : } \Psi_\alpha(x) = \begin{cases} e^{-(-x)^{(-\alpha)}} & (x < 0) \\ 1 & (x \geq 0). \end{cases}'$$

With $\alpha < 0$;

$$(iii) \text{ Gumbel : } \Lambda(x) = e^{-e^{-x}}, \quad x \in \mathbb{R}.$$

It is convenient to use a common parametrization for the three types, as in the following statement (the verification is left to the reader):

Corollary 1.3.5

If G is a max-stable distribution, then $\exists \mu \in \mathbb{R}, \sigma > 0, \gamma \in \mathbb{R}$, such that

$$G(x) = G_{\mu, \sigma, \gamma}(x) := \exp \left[- \left(1 + \gamma \left(\frac{x - \mu}{\sigma} \right) \right)_+^{-1/\gamma} \right], \quad (1.11)$$

where $y_+ = \max(y, 0)$, and where the above expression for $\gamma = 0$ is understood as its limit as $\gamma \rightarrow 0$, that is

$$G(x) = \exp \left[-e^{-\frac{x-\mu}{\sigma}} \right].$$

Also,

- $\gamma = 0$ if and only if G is of Gumbel type,
- $\gamma > 0$ if and only if G is of Fréchet type Φ_α with $\alpha = 1/\gamma$,
- $\gamma < 0$ if and only if G is of Weibull type Ψ_α with $\alpha = 1/\gamma$.

Before some examples and the proof, Figures 1.2, 1.3 and 1.4 illustrate the three types. The first two figures explain why the distribution functions in the Fréchet domain of attraction are usually referred to as *heavy tailed*, whereas those in the Gumbel domain are called *light tailed* (There is no agreement about the Weibull domain. Some authors use ‘light tails’, some others use ‘bounded tails’). Also, Figure 1.4 indicates that a series of *i.i.d.* observations of heavy tailed variables is likely to contain more ‘extreme’ events than a series of light tailed variables: The Fréchet type corresponds to situation where extreme events occur ‘quite often’. Typical examples include river discharge data, rainfall (in some cases), financial return times series, insurance claims.

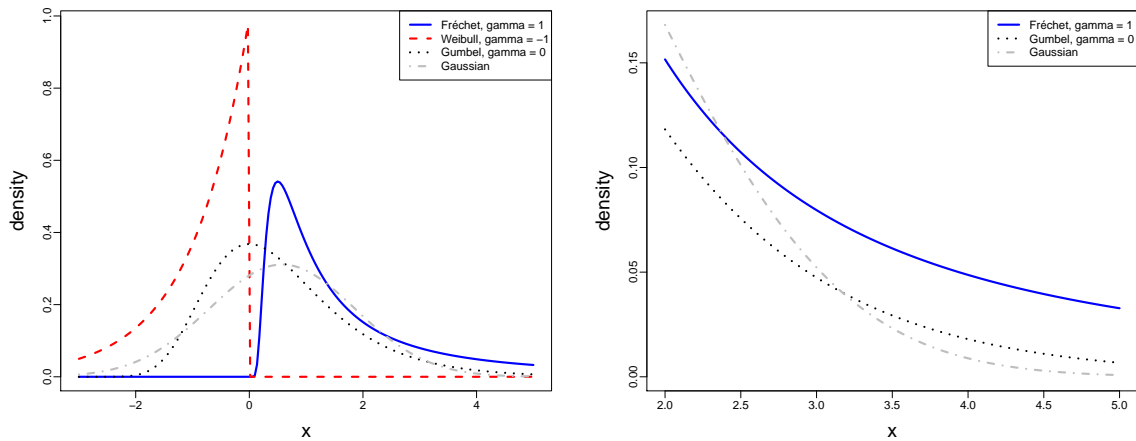


Figure 1.2: Density plot for the three extremal types, respectively $(\gamma = 1, \mu = 1, \sigma = 1)$, $(\gamma = -1, \mu = -1, \sigma = 1)$, $(\gamma = 0, \mu = 0, \sigma = 1)$; compared with the Gaussian density with same mean and variance as the Gumbel one. The right panel is a zoom on the tail.

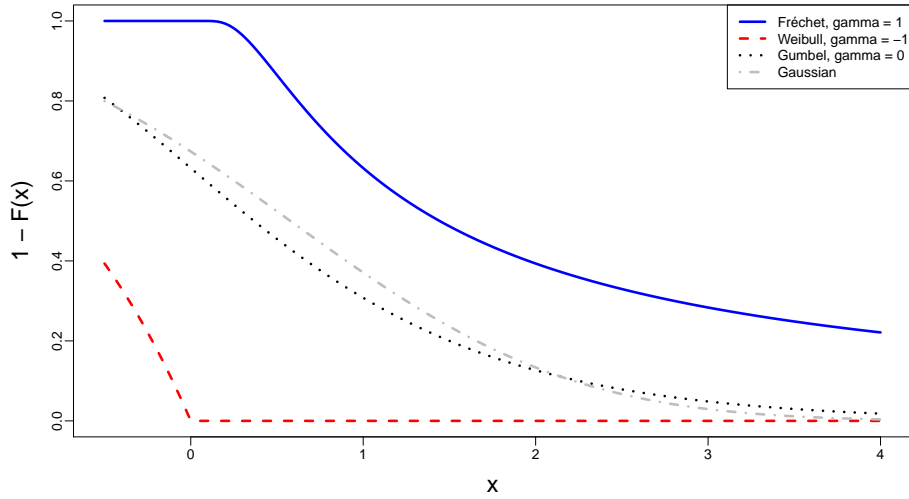


Figure 1.3: Survival function $1 - F(x)$ for the three extremal types, respectively $(\gamma = 1, \mu = 1, \sigma = 1)$, $(\gamma = -1, \mu = -1, \sigma = 1)$, $(\gamma = 0, \mu = 0, \sigma = 1)$; compared with the Gaussian survival function with same mean and variance as the Gumbel one.

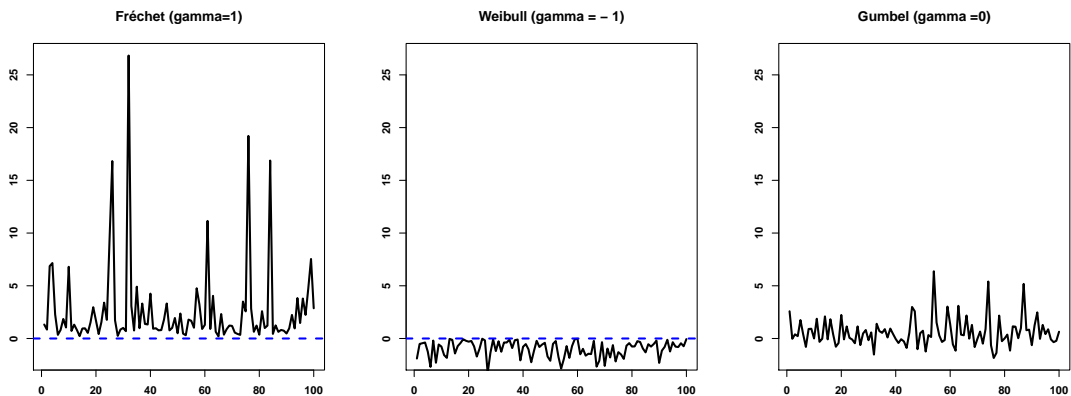


Figure 1.4: Series of *i.i.d.* random variables of the three extremal types, respectively $(\gamma = 1, \mu = 1, \sigma = 1)$, $(\gamma = -1, \mu = -1, \sigma = 1)$, $(\gamma = 0, \mu = 0, \sigma = 1)$

Example 1.1 (Exponential variable, Gumbel domain):

Let F be an exponential distribution,

$$F(x) = \mathbb{1}_{x>0} (1 - e^{-\lambda x}).$$

In order to 'guess' possible norming constant, we shall proceed with heuristic computations, and prove in a second step that the sequences are indeed suitable. We may assume that for $x > 0$, $a_n x + b_n \xrightarrow[n \rightarrow \infty]{} \infty$ (otherwise,, $F^n(a_n x + b_n) \xrightarrow[n \rightarrow \infty]{} 0$). Thus

$$\begin{aligned} F^n(a_n x + b_n) &= \mathbb{1}_{a_n x + b_n > 0} (1 - e^{-\lambda(a_n x + b_n)})^n \\ &= \mathbb{1}_{a_n x + b_n > 0} \exp\left(n \log(1 - e^{-\lambda a_n x - \lambda b_n})\right) \\ &\approx \mathbb{1}_{a_n x + b_n > 0} \exp\left(n e^{-\lambda a_n x - \lambda b_n}\right) \\ &= \mathbb{1}_{a_n x + b_n > 0} \exp\left(e^{-\lambda a_n x + \log n - \lambda b_n}\right) \end{aligned}$$

If we set $a_n = 1, b_n = \lambda^{-1} \log n$, the latter expression does converge to $G(x) = \exp(-e^{-\lambda x})$, which is of Gumbel type. Now we only need to check that the (MDA') condition is indeed satisfied with these sequences: for $x \in \mathbb{R}$,

$$\begin{aligned} F^n(a_n x + b_n) &= \mathbb{1}_{x + \log n / \lambda > 0} (1 - e^{-\lambda(x + \log(n)/\lambda)})^n \\ &= \exp\left(n \log(1 - e^{-\lambda x - \log(n)})\right) \quad (n \geq e^{-\lambda x}) \\ &= \exp\left(n \log\left(1 - \frac{e^{-\lambda x}}{n}\right)\right) \\ &= \exp\left(n \left(-\frac{e^{-\lambda x}}{n} + o(1/n)\right)\right) \\ &\xrightarrow[n \rightarrow \infty]{} \exp(-e^{-\lambda x}). \end{aligned}$$

Exercise 1.2 (Domains of attraction):

Find the domain of attraction and appropriate norming sequences a_n, b_n for

1. A standard uniform distribution $F(x) = x(0 < x < 1)$
2. A Pareto distribution $F(x) = 1 - \left(\frac{u}{x}\right)^\alpha \quad (x > u, \alpha > 0)$.

Proof of Theorem 1.3.4. Our proof mainly follows [Resnick \(1987\)](#).

Let $\alpha > 0, \beta$ the norming functions such that for $t > 0, x \in \mathbb{R}$,

$$G(x) = G^t(\alpha(t)x + \beta(t)). \tag{1.12}$$

The key to the proof is to show that α and β satisfy a particular functional equation (the Hamel equation, see below), which solutions are known, and then to obtain the expression of G using (1.12) again.

First, for $t, s > 0, x \in \mathbb{R}$,

$$G^{1/(ts)}(x) = G(\alpha(ts)x + \beta(ts)).$$

but also

$$G^{1/(ts)}(x) = [G^{1/s}(x)]^{1/t} = G^{1/t}(\alpha(s)x + \beta(s)) = G(\alpha(t)\alpha(s)x + \alpha(t)\beta(s) + \beta(t)).$$

By Lemma 1.3.3, this implies that for $t, s > 0$,

$$\alpha(ts) = \alpha(t)\alpha(s) \tag{1.13}$$

$$\beta(ts) = \alpha(t)\beta(s) + \beta(t) = \alpha(s)\beta(t) + \beta(s), \tag{1.14}$$

where the last equality follows by interchanging the roles of s and t .

One recognizes in (1.13) the Hamel equation. It is easy to prove that the only continuous solutions of this equation are of the form $f(t) = t^\gamma$, for some $\gamma \in \mathbb{R}$ (this is obvious for $\log t \in \mathbb{N}$, then by inversion also for $\log t \in \mathbb{Q}$, and continuity achieves the proof for $t \in \mathbb{R}$.) In fact, it may be shown (See Hahn and Rosenthal (1948), pp. 116-118) that the only measurable solutions are also of this kind. Now, by 1.3.3, we know that α and β are measurable. Whence, $\exists \gamma \in \mathbb{R}$:

$$\forall t > 0, \quad \alpha(t) = t^\gamma$$

We distinguish three cases according to the sign of γ (to wit, γ will be the extreme value index appearing in (1.11))

case 1: $\gamma = 0$ In this case $\alpha \equiv 1$. Thus (1.14) yields $\beta(ts) = \beta(t) + \beta(s)$, $s, t > 0$. This is again the Hamel equation (up to log-scaling, that is: e^β satisfies (1.13)). Consequently, for some $\sigma \in \mathbb{R}$, $e^{\beta(t)} = t^\sigma$ (to wit, σ will be the scale parameter in (1.11)), that is

$$\beta(t) = \sigma \log t, \quad s, t > 0. \tag{1.15}$$

Going back to (1.12), we have

$$G^{1/t}(x) = G(x + \sigma \log t), \quad x \in \mathbb{R}, t > 0.$$

For x such that $0 < G(x) < 1$ (which exists by non-degeneracy of G), the function $t \mapsto G^{1/t}(x)$ is strictly increasing on $]1, \infty[$, thus $t \mapsto \sigma \log t$ must be strictly increasing, which means $\sigma > 0$. Then (1.12) with $x = 0$ yields $\forall t > 0, G(\sigma \log t) = G(0)^{1/t}$, i.e., with $u = \sigma \log t$,

$$\forall u \in \mathbb{R}, G(u) = (G(0))^{e^{-u/\sigma}}$$

necessarily, $0 < G(0) < 1$, otherwise G would be constant on \mathbb{R} . Thus

$$\forall u \in \mathbb{R}, \quad G(u) = \exp \left[-e^{-u/\sigma} (-\log G(0)) \right] = \exp \left[-e^{-(u-\mu)/\sigma} \right]$$

where μ is chosen so that $e^{\mu/\sigma} = -\log G(0)$, i.e. $\mu = \sigma \log(-\log G(0))$. Thus G is of Gumbel type ($G(x) = \Lambda((x - \mu)/\sigma)$).

case 2 : $\gamma \neq 0$ In this case, identity (1.14) implies, for $s, t > 0$,

$$\beta(t)(s^\gamma - 1) = \beta(s)(t^\gamma - 1).$$

Thus $t \mapsto \beta(t)/(t^\gamma - 1)$ (for $t \neq 1$) is constant, i.e.

$$\exists C \in \mathbb{R} : \quad \beta(t) = C(t^\gamma - 1) \quad (t \neq 1).$$

Going back to (1.12), we obtain, for $x \in \mathbb{R}$,

$$G^{1/t}(x) = G(t^\gamma x + C(t^\gamma - 1)) = G[t^\gamma(x + C) - C],$$

so that $G^{1/t}(x - C) = G[t^\gamma x - C]$. Whence, putting $\Gamma(x) = G(x + C)$,

$$\Gamma^{1/t}(x) = \Gamma(t^\gamma x), \quad t > 0, x \in \mathbb{R}. \quad (1.16)$$

Note that this implies (setting $x = 0$ in the above equation) that $\Gamma(0) \in \{0, 1\}$. Also, $\Gamma(1) > 0$, otherwise Γ would be identically equal to 0. To conclude, it is enough to show that Γ is of one of the two first types (Fréchet or Gumbel). This will depend on the sign of γ .

1. **Case $\gamma > 0$** Let us prove that we must have $\Gamma(1) < 1$: otherwise we would have for $t > 0$, $1 = \Gamma(t^\gamma)$, so that $\Gamma(0) = \lim_{t \rightarrow 0} \Gamma(t^\gamma) = 1$. But then $\exists x < 0$ such that $0 < \Gamma(x) < 1$, and for such an x the function $t \mapsto \Gamma^{1/t}(x)$ is strictly increasing. However, $\Gamma^{1/t}(x) = \Gamma(t^\gamma x)$, which is a non increasing function of t , a contradiction. Thus $0 < \Gamma(1) < 1$.

We may thus rewrite (1.16) as (with $u = t^\gamma$, and $x = 1$)

$$\Gamma(u) = \Gamma(1)^{u^{-1/\gamma}} = \exp \left[-u^{-1/\gamma} (-\log \Gamma(1)) \right] = \exp \left[-(u/\sigma)^{-1/\gamma} \right], \quad u > 0. \quad (1.17)$$

with $\sigma = (-\log \Gamma(1))^\gamma$. Thus $G(x) = \Gamma(x + C) = \Phi_{1/\gamma}((x + C)/\sigma)$ (Fréchet type).

2. **Case $\gamma < 0$:** with a similar argument, one obtains that G is of the Weibull type. ■

Remark 1.3.6 (Choice of norming sequences and parameters of the limit). *If F satisfies a MDA condition for some sequences (a_n, b_n) and if the limit is of the form $G_{\mu, \sigma, \gamma}(x)$ as in (1.11), then it is always possible to choose other sequences a'_n, b'_n such that*

$$F^n(a'_n x + b'_n) \xrightarrow{w} G_{0,1,\gamma}$$

where $G_{0,1,\gamma}(x) = \exp \left(-(1 + \gamma x)_+^{-1/\gamma} \right)$. *Indeed, one may choose $a'_n = \sigma a_n, b'_n = b_n + \mu a_n$, and use the convergence to type lemma 1.2.7.*

Remark 1.3.7 (Continuity set of the limit). *Since the max-stable distributions are continuous on \mathbb{R} (this is obvious from their parametric form (1.11)), if F is in the domain of attraction of G , then convergence must occur for all $x \in \mathbb{R}$. In other words, in this case, weak convergence is the same as pointwise convergence on \mathbb{R} .*

1.4 Case study

The common idea between most statistical applications is to use the limits in the different convergence results presented in the above sections as *models* for the extremal data, where ‘extremal’ can be understood either as ‘a maximum over a long period’ (as in the present chapter) or ‘an excess above a high threshold’ (as shown in the next chapter).

1.4.1 Annual maximum of the sea level

In order to fix a reasonable premium for real estate insurance, an insurance company is interested to potential damage induced from floods in a city close to the sea level. A dike does protect the city as long as the sea level is below some fixed level u_0 . The question is : what is the probability of a flood occurring during a given year ? It may be shown that under weak temporal dependence (with mixing conditions), the extreme value theorem still holds. Thus, one may use the approximation for the annual maximum M_n ($n = 365$):

$$\frac{M_n - b_n}{a_n} \underset{d}{\approx} Z$$

where $Z \sim G$ is a standard EV distribution, $G(x) = e^{-(1+\gamma x)^{-1/\gamma}}$, and a_n, b_n are unknown parameters. In other words, dropping the index n (which is fixed to 365), and setting $\mu = b_n$, $\sigma = a_n$ the assumption is

$$\mathbb{P}(M \leq x) = \mathbb{P}((M - \mu)/\sigma \leq (x - \mu)/\sigma) \simeq G((x - \mu)/\sigma) = \exp \left[- \left(1 + \gamma \frac{x - \mu}{\sigma} \right)_+^{-1/\gamma} \right].$$

Thus, we assume that $M \sim G_{\mu, \sigma, \gamma}$ for some unknown (μ, σ, γ) ; in other words the statistical model for M is the parametric model

$$\mathcal{P} = \{G_{\mu, \sigma, \gamma} : \mu \in \mathbb{R}, \sigma > 0, \gamma \in \mathbb{R}\}$$

A widely used approach for inference of the is the maximum likelihood approach. It is implemented in numerous R models such as `ismev`, `extRemes`, `evd`, `fExtremes`, `EVIM`, `Xtremes`, `HYFRAN`, `EXTREMES` ... In our examples, we mainly use `evd` and `ismev`. Notice that it is also possible to resort to probability weighted moment methods. The dataset `portpirie` is part of these two packages. It contains annual maxima of the sea level at Port Pirie (Australia) (Figure 1.5), where a disastrous flood occurred in 1934 (Figure 1.6).

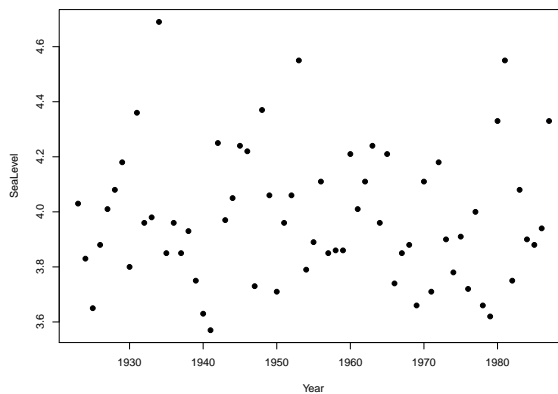


Figure 1.5: `portpirie` data in package `evd`: Annual maxima of the sea level at Port Pirie, 1923-1987



Figure 1.6: 1934 flood at Port Pirie, Australia

The next few lines of code show how to proceed with MLE estimation and obtain diagnostic plots (Figure 1.4.1).

```
> library(evd)
> fitgevpirie <- fgev(portpirie)
> fitgevpirie

Call: fgev(x = portpirie)
Deviance: -8.678117

Estimates
   loc      scale  shape
3.87475 0.19805 -0.05012

Standard Errors
   loc      scale  shape
0.02793 0.02025 0.09826

Optimization Information
Convergence: successful
Function Evaluations: 30
Gradient Evaluations: 8

> plot(fitgevpirie)
```

The probability of an excess of any threshold u may now reasonably be estimated by a

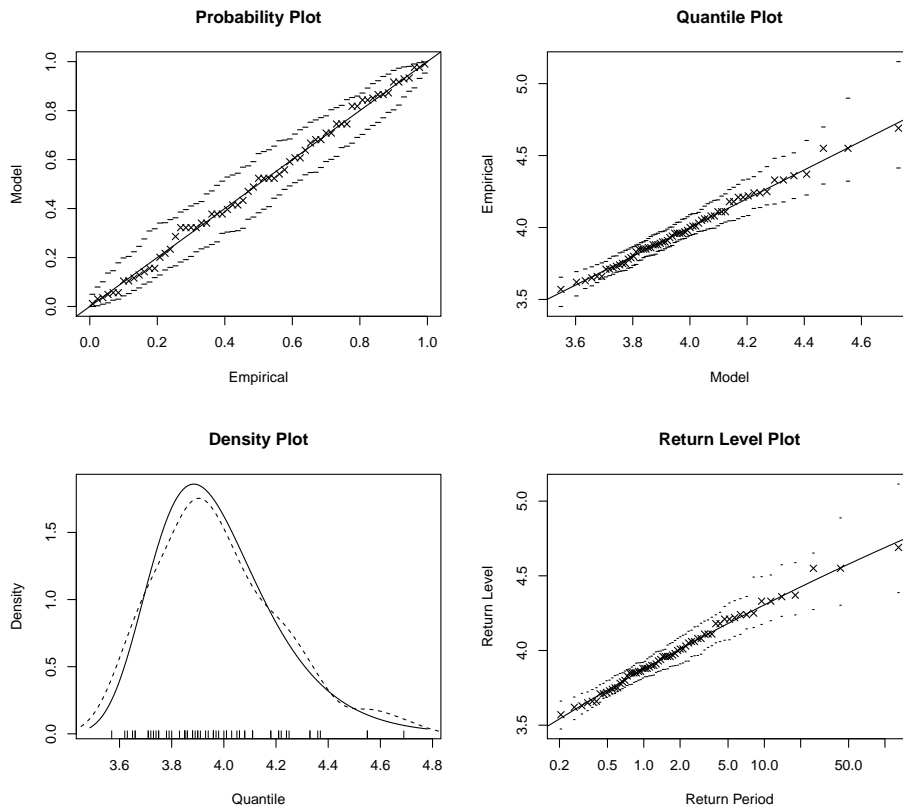


Figure 1.7: Graphical diagnostic plot for the GEV model fit on the Port Pirie dataset, as provided by R package `evd`.

plugin method,

$$\hat{p} = 1 - G_{\hat{\mu}, \hat{\sigma}, \hat{\gamma}}(u).$$

If the goal was to estimate a high quantile, say $z_p = F_n^{\leftarrow}(1-p)$, where F_n is the distribution of the annual maximum, one could again use plugin estimates and set

$$\hat{z}_p = G_{\hat{\mu}, \hat{\sigma}, \hat{\gamma}}^{\leftarrow}(1-p) = \begin{cases} \hat{\mu} + \frac{\hat{\sigma}}{\hat{\gamma}} \left[\left(\frac{-1}{\log(1-p)} \right)^{\hat{\gamma}} - 1 \right] & (\hat{\gamma} \neq 0), \\ \mu + \sigma \log \left(\frac{-1}{\log(1-p)} \right) & (\hat{\gamma} = 0). \end{cases} \quad (1.18)$$

In this introductory course, will not get into details about the consistency of these estimators. However, one may notice that, on this example, the maximum likelihood estimate is close to 0, compared to its estimated standard deviation. One may thus wonder if the Gumbel sub-model ($\gamma = 0$) provides a reasonable fit (this will impact in particular high quantile estimates, since the Gumbel distribution has unbounded support, contrary to the Weibull).

A simple visual diagnostic for this hypothesis is the following: The inverse of $G(x) = e^{-e^{-\frac{x-\mu}{\sigma}}}$ is

$$G^{\leftarrow}(y) = \sigma [-\log(-\log(y))] + \mu.$$

On the other hand, the empirical quantile of order $y = i/n$ ($i = 1, \dots, n$) is

$$\hat{G}^{\leftarrow}(i/n) = X_{(i)}$$

(the i^{th} order statistic)

If the Gumbel model is appropriate, we should have

$$X_{(i)} \approx \sigma - \log\left(-\log\left(\frac{i}{n+1}\right)\right) + \mu,$$

for some $\sigma > 0$ and some $\mu \in \mathbb{R}$. Thus the graph of the points $(-\log(-\log(\frac{i}{n+1})); X_{(i)})$ (the so-called *Gumbel plot*) should be approximately affine. The graph obtained with the Port Pirie data is shown in Figure 1.4.1. It ‘confirms’ the null hypothesis of a Gumbel type distribution.

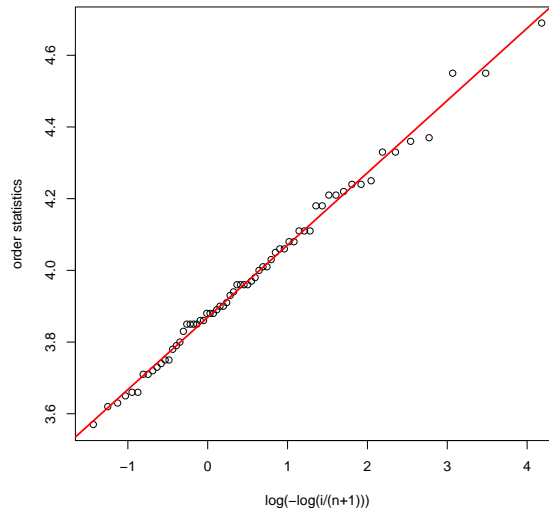


Figure 1.8: Gumbel plot for the Port Pirie dataset.

1.4.2 Method of block maxima

This is just a generalization of the above analysis. Given a series of n independent (or ‘weakly’ dependent), say daily, data $X_i, i \leq n$, the analyst may divide the data set into m block of size $k = n/m$ each (say $k = 30$ to work with monthly maxima), and assume that the maximum over each block

$$M_i = \bigvee_{r=ki+1}^n X_r, \quad i = 1, \dots, m$$

approximately follows a GEV distribution, which parameters remain to be estimated. The rest follows the line of the Port Pirie example. Figure 1.4.2 illustrates this procedure.

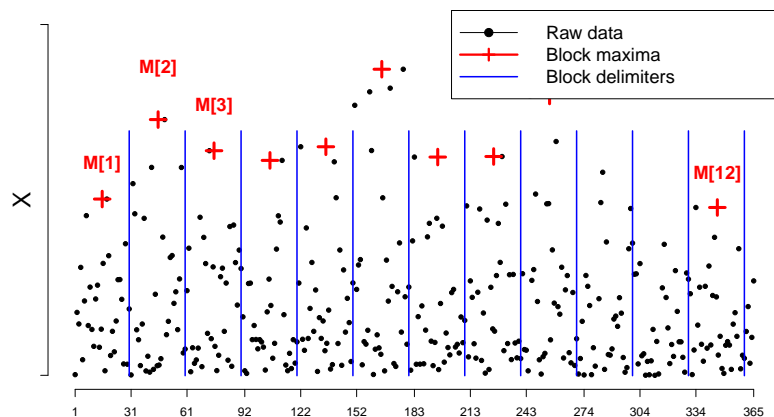


Figure 1.9: Work-flow for the block-maxima method.

Exercise 1.3 (Domains of attraction: illustration):

Hint: Results from Exercise 1.2 will be useful.

1. Illustrate the phenomenon of weak convergence stated in Fisher and Tipett's theorem through the convergence of histograms (built from a random sample) of maxima towards histograms of the limit, for a negative shape parameter:
 - Choose a textbook distribution F in the Weibull domain of attraction and find appropriate norming sequences a_n, b_n such that (MDA) holds.
 - Write a short code allowing to:
 - generate M blocks of size n of independent random variables distributed according to F and normalize the block maxima ;
 - plot a histogram of the M normalized maxima and superimpose the histogram for the limit distribution in a visually illustrative manner.
 - Let M and n vary so as to illustrate weak convergence of maxima as $M \rightarrow \infty$. Explain the role of M and n in what you observe. Summarize the results in a figure including ≈ 6 such histograms with different values of M and a single (appropriate) value of n .
2. show (graphically and numerically) uniform convergence of c.d.f.'s. Explain why (i.e. prove that) weak convergence of normalized maxima indeed implies uniform convergence of c.d.f.'s
3. Change the input distribution and work with a translated Pareto distribution, $\mathbb{P}(X > x) = ((x - \beta)/u)^\alpha$, on some for some $\alpha > 0, \beta, u \in \mathbb{R}, x \geq u + \beta$. Draw similar outputs as in the previous questions and compare the rate of convergence.
4. With the distribution from question 1 or 3, generate a dataset of an appropriate size and estimate the GEV parameters with a maximum-likelihood method. discuss the convergence towards the true parameters.

Hand out a notebook (R or Python) with maths, code and results.

Chapter 2

Peaks-Over-Thresholds and Regular variation

2.1 Equivalent formulations in terms of excesses above thresholds

Our goal is to show that the condition **(MDA')** is equivalent to the convergence of the conditional distribution of excesses above t , in the following sense

Theorem 2.1.1 (Balkema, de Haan, 1974)

The following statements are equivalent

$$(i) \exists a_n > 0, b_n: \text{ for all } x \in \mathbb{R}, F^n(a_n x + b_n) \xrightarrow[n \rightarrow \infty]{} e^{-(1+\gamma x)_+^{-1/\gamma}}$$

$$(ii) \exists \sigma : (0, \infty) \rightarrow (0, \infty) \text{ such that, for each } x \text{ such that } 1 + \gamma x > 0,$$

$$\mathbb{P} \left(\frac{X - t}{\sigma(t)} > x \mid X > t \right) \xrightarrow[t \nearrow x_*]{} -\log G(x) = (1 + \gamma x)_+^{-1/\gamma}, \quad (2.1)$$

where $x_* = F^{\leftarrow}(1)$ is the right end-point of the support of F ; which means in terms of distribution functions that

$$\frac{1 - F(t + \sigma(t)x)}{1 - F(t)} \xrightarrow[t \nearrow x_*]{} (1 + \gamma x)_+^{-1/\gamma}. \quad (2.2)$$

In such a case, σ may be chosen as $\sigma(t) = a \left(\frac{1}{1 - F(t)} \right)$.

For the proof, we will use a series of equivalent characterization of the **(MDA')** condition in terms of survival functions $1 - F$ and inverse functions.

Lemma 2.1.2 (Convergence of survival functions)

*The **(MDA')** condition is satisfied if and only if*

$$n(1 - F(a_n \bullet + b_n)) \xrightarrow{w} -\log G.$$

Proof. By continuity of the logarithm function and its inverse,

$$\mathbf{(MDA')} \iff n \log F(a_n \bullet + b_n) \xrightarrow{w} \log G.$$

Now on both sides, for x such that $\log G(x)$ is finite, $F(a_n x + b_n)$ must converge to 1, thus

$$\log F(a_n x + b_n) = \log(1 - (1 - F(a_n x + b_n))) \sim_{n \rightarrow \infty} -[1 - F(a_n x + b_n)],$$

whence the result. \blacksquare

An immediate consequence is that (MDA') is equivalent to

$$\frac{1}{n(1 - F(a_n \cdot + b_n))} \xrightarrow{w} \frac{-1}{\log G}. \quad (2.3)$$

Let $U = \left(\frac{1}{1-F}\right)^{\leftarrow}$ (i.e. $U(y) = F^{\leftarrow}(1 - 1/y), y > 0$) and $\Gamma = \frac{-1}{\log G}$. From Lemma 1.2.5.

$$(2.3) \iff \frac{U(n \cdot) - b_n}{a_n} \xrightarrow{w} \Gamma^{\leftarrow} \quad \text{as } n \rightarrow \infty \quad (2.4)$$

Define $a(t) = a_{[t]}, b(t) = b_{[t]}, t > 0$. The next lemma extends the above equality to all $t > 0$.

Lemma 2.1.3

The (MDA') condition is satisfied if and only if

$$\frac{U(t \cdot) - b(t)}{a(t)} \xrightarrow{w} \Gamma^{\leftarrow}, \quad \text{as } t \rightarrow \infty \quad (2.5)$$

Proof. We only need to show that (MDA') implies (2.5). Indeed, the converse is immediate from (2.4).

Let $y \in \mathcal{C}(\Gamma^{\leftarrow})$. By monotonicity of U ,

$$\frac{U([t]y) - b(t)}{a(t)} \leq \frac{U(ty) - b(t)}{a(t)} \leq \frac{U([t] + 1)y - b(t)}{a(t)} \quad (2.6)$$

Fix $\epsilon > 0$, and choose $y' > y$ such that $\Gamma^{\leftarrow}(y') < \Gamma^{\leftarrow}(y) + \epsilon$. Then for some t_0 large enough and $t > t_0$, $([t] + 1)y < [t]y'$. Thus for large t , $\frac{U([t] + 1)y - b(t)}{a(t)} \leq \frac{U([t]y') - b(t)}{a(t)} \rightarrow \Gamma^{\leftarrow}(y') \leq \Gamma^{\leftarrow}(y) + \epsilon$. Since the limit of the left-hand side of (2.6) is $\Gamma^{\leftarrow}(y)$, and since ϵ is arbitrary, the proof is complete. \blacksquare

Remark 2.1.4 (Continuity points of Γ^{\leftarrow}). Notice that weak convergence in (2.4) and (2.5) is equivalent to pointwise convergence for $y > 0$. Indeed, $\Gamma = -1/\log G$ induces a bijection (it is strictly increasing and continuous) from the interior of its support onto $(0, \infty)$. Thus, its left inverse is a real inverse and is also continuous on $(0, \infty)$.

We may now proceed with the proof of the main result of this section.

Proof of Theorem 2.1.1. We prove that (MDA') implies (2.2); the proof of the converse is similar and is left as an exercise. Put $\sigma(t) = a\left(\frac{1}{1-F(t)}\right)$. It is easily verified that the left-continuous inverse of the function

$$x \mapsto \frac{1 - F(t)}{1 - F(t + x\sigma(t))}$$

is

$$y \mapsto \frac{U\left(\frac{y}{1-F(t)}\right) - t}{\sigma(t)}.$$

Using Lemma 1.2.5 and Remark 2.1.4, it is thus enough to show that

$$\forall y \geq 1, \quad \frac{U\left(\frac{y}{1-F(t)}\right) - t}{\sigma(t)} \xrightarrow[t \nearrow x_*]{} \frac{y^\gamma - 1}{\gamma} := \Gamma^{\leftarrow}(y). \quad (2.7)$$

However, using (2.5) from Lemma 2.1.3 for $y = 1$, we have

$$\frac{U(T) - b(T)}{a(T)} \xrightarrow{T \rightarrow \infty} \Gamma^{\leftarrow}(1) = \frac{1^\gamma - 1}{\gamma} = 0$$

But also for $y > 0$,

$$\frac{U(Ty) - b(T)}{a(T)} \xrightarrow{T \rightarrow \infty} \frac{y^\gamma - 1}{\gamma}.$$

By subtraction,

$$\frac{U(Ty) - U(T)}{a(T)} \xrightarrow{T \rightarrow \infty} \frac{y^\gamma - 1}{\gamma}. \quad (2.8)$$

N.B: If we could replace T with $1/(1 - F(t))$, and t with $U(T)$ in (2.8), we would obtain (2.7) and the proof would be complete. This is the idea behind the remainder of the proof.

It is easy to show that if f is a right-continuous, non decreasing function, for $\epsilon > 0$, we have $f^{\leftarrow}(f(t)) \leq t \leq f^{\leftarrow}(f(t) + \epsilon)$. Thus, for $y > 0, 0 < t < x_*$,

$$\begin{aligned} 0 &\leq \frac{t - U\left(\frac{1}{1-F(t)}\right)}{a\left(\frac{1}{1-F(t)}\right)} \leq \frac{U\left(\frac{1}{1-F(t)} + \epsilon\right) - U\left(\frac{1}{1-F(t)}\right)}{a\left(\frac{1}{1-F(t)}\right)} \\ &\leq \frac{U\left(\frac{1}{1-F(t)}(1 + \epsilon)\right) - U\left(\frac{1}{1-F(t)}\right)}{a\left(\frac{1}{1-F(t)}\right)} \\ &\xrightarrow[t \nearrow x_*]{} \Gamma^{\leftarrow}(1 + \epsilon) = \frac{(1 + \epsilon)^\gamma - 1}{\gamma}, \end{aligned} \quad (2.9)$$

where the last limit is obtained from (2.8) and the fact that $1/(1 - F(t)) \xrightarrow[t \nearrow x_*]{} +\infty$ (indeed, in case $x_* < \infty$, F cannot have a jump at x_* , see *e.g.* Leadbetter et al. (2012), Corollary 1.5.2). Since ϵ is arbitrary small, we conclude that

$$\frac{t - U\left(\frac{1}{1-F(t)}\right)}{a\left(\frac{1}{1-F(t)}\right)} \xrightarrow[t \nearrow x_*]{} 0. \quad (2.10)$$

As a consequence, for $y > 0$,

$$\begin{aligned} \frac{U\left(\frac{y}{1-F(t)}\right) - t}{\sigma(t)} &\underset[t \nearrow x_*]{\sim} \frac{U\left(\frac{y}{1-F(t)}\right) - U\left(\frac{1}{1-F(t)}\right)}{\sigma(t)} \\ &\xrightarrow[t \nearrow x_*]{} \frac{y^\gamma - 1}{\gamma}, \end{aligned}$$

where the last limit is obtained from (2.8) as in (2.9). This shows (2.7) and completes the proof. \blacksquare

2.2 The ‘Peaks-Over-Threshold’ inference method

The ‘Peaks-Over-Threshold’ (POT) methods consider excesses over a fixed, relatively high threshold, instead of maxima. Consider the equivalent condition of (MDA) in terms of excesses above thresholds (2.1) (Theorem 2.1.1),

$$\frac{1 - F(t + \sigma(t) \cdot)}{1 - F(t)} \xrightarrow[t \nearrow x_*]{} (1 + \gamma \cdot)_+^{-1/\gamma}.$$

For fixed, large enough t (but not too large, in order to observe ‘some’ data above t), we may use the approximation

$$\frac{1 - F(t + \sigma x)}{1 - F(t)} \approx (1 + \gamma x)_+^{-1/\gamma}.$$

In other terms, if $X \sim F$,

$$\mathbb{P}((X - t)/\sigma > x \mid X > t) \approx (1 + \gamma x)_+^{-1/\gamma}.$$

or, by a change of variables

$$\mathbb{P}(X - t > x \mid X > t) \approx \left(1 + \gamma \frac{x}{\sigma}\right)^{-1/\gamma}, \quad x > 0$$

for some unknown parameters (σ, γ) .

2.2.1 Parametric estimation in the GPD model

Consider an *i.i.d.* sample $X_i, i = 1, \dots, n \sim F$. Estimation of the parameters (σ, γ) may be done using the *excesses* above t ,

$$\{X_i : X_i > t, i = 1, \dots, n\},$$

as illustrated in Figure 2.2.1 .

Let $(i(1), \dots, i(m))$ be the indices corresponding to an excess. Now the assumption for further inference is, for $1 \leq r \leq m$,

$$\mathbb{P}\left(X_{i(r)} > x\right) \approx \left(1 + \gamma \frac{x - t}{\sigma}\right)_+^{-1/\gamma}, \quad x > t. \quad (2.11)$$

i.e. $X_{i(r)} \sim H_{t, \sigma, \gamma}(y)$, where $H_{\mu, \sigma, \gamma}$ is the *Generalized Pareto distribution* (GPD) with parameters $\mu \in \mathbb{R}, \sigma > 0, \gamma \in \mathbb{R}$,

$$H_{\mu, \sigma, \gamma}(x) = 1 - \left(1 + \gamma \frac{x - \mu}{\sigma}\right)_+^{-1/\gamma}, \quad x > \mu.$$

Notice that in (2.11), the location parameter is automatically $\mu = t$. Also, the above quantity for $\gamma = 0$ should be interpreted as its limit as $\gamma \rightarrow 0$,

$$H_{\mu, \sigma, 0}(x) = 1 - e^{-\frac{x - \mu}{\sigma}} \quad (x > \mu).$$

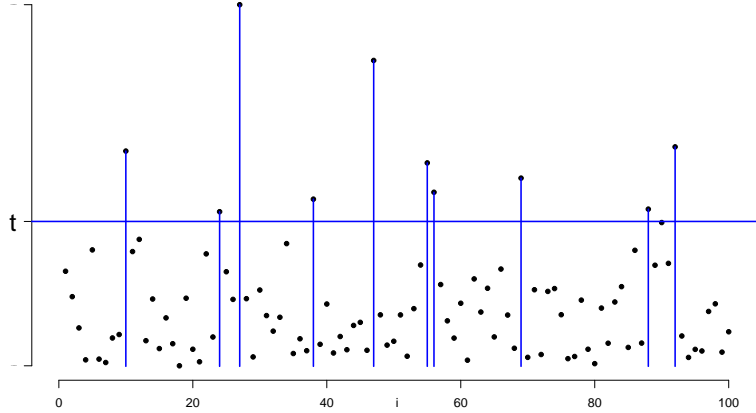


Figure 2.1: Work-flow for the POT procedure above a high threshold t : the raw data are the black dots, the ‘excess’ data $X_{i(r)}$ used for inference correspond to the blue lines.

The GPD model for the excesses $(X_i(r), r = 1, \dots, m)$ is thus

$$\mathcal{P} = \{H_{t,\sigma,\gamma} : \sigma > 0, \gamma \in \mathbb{R}\}.$$

Again, the packages mentioned in the Port Pirie example provide routines for maximum likelihood estimation in the GPD model. In practice, one may use the estimated parameters in a plugin method in order to predict the probability of an excess above a high threshold $t' > t$ (even though no data has ever been observed above t'). It is common practice to estimate $\zeta := 1 - F(t)$ empirically and to neglect the estimation error:

$$\hat{\zeta} = \mathbb{P}_n(t, \infty) = \frac{1}{n} \sum_{i=1}^n \mathbb{1}_{X_i > t}.$$

This yields

$$1 - F(t + x) \approx \hat{\zeta} \left(1 + \gamma \frac{x}{\sigma}\right)_+^{-1/\gamma}, \quad x \geq 0. \quad (2.12)$$

2.2.2 High quantile estimation in the GPD model

If the quantity of interest is a high quantile, the GPD model provides a straightforward plug-in approach to estimation of (out-of-sample) high quantiles, as an alternative to the block-maxima approach leading to the estimator (1.18). Consider again the $(1 - p)$ quantile of the annual maximum of daily observation, denoted by z_p . Assume for simplicity independence between daily observations X_i and that F , the distribution of X_1 , is invertible. By definition $F^m(z_p) = 1 - p$ (with $m = 365$) thus $F(z_p) = (1 - p)^{1/m} \approx e^{-p/m} \approx 1 - p/n$ for small p . Thus $z_p \approx \tilde{z}_p = F^{\leftarrow}(1 - p/m)$. For small p/m , and if F indeed satisfies (MDA'), the GPD approximation is appropriate for F , and thus also for F^{\leftarrow} (e.g. in the sense of Lemma 2.1.3). Given parameter estimates $(\hat{\sigma}, \hat{\gamma})$ in the GPD model (2.11), and an empirical estimate $\hat{\zeta}$ of the probability of an excess above t , a plug-in estimate for \tilde{z}_p is thus obtained by solving (in

x)

$$\hat{\zeta}\left(1 + \gamma \frac{x-t}{\hat{\sigma}}\right)_+^{-1/\hat{\gamma}} = 1 - p/m,$$

which yields

$$\hat{z}_{p,GPD} = t + \frac{\hat{\sigma}}{\hat{\gamma}} \left(\left(\frac{\zeta}{p/m} \right)^{\hat{\gamma}} - 1 \right). \quad (2.13)$$

Notice that we consider the case $\hat{\gamma} \neq 0$ which is almost surely the case with maximum likelihood estimates.

2.2.3 Threshold choice for POT models

Several graphical diagnostic tools exist. Here we consider the Mean Residual life plot. The Mean (expected) residual life above threshold u (for $0 < \gamma < 1$) is defined as

$$MRL(t) = E(X - t | X > t)$$

Proposition 2.2.1

If $\mathcal{L}[X - t_0 | X > t_0]$ ('the conditional distribution of $X - t_0$ given that $X > t_0$ ') is $H_{0,\sigma(t_0),\gamma}$, with $\gamma < 1$, then $MRL(t)$ is linear w.r.t. t for $t > t_0$.

Proof. Let $Y \sim H_{0,\sigma,\gamma}$. Then integrating the survival function of Y yields $E(Y) = \frac{\sigma}{1-\gamma}$.

Also under the assumptions of the statement, a direct computation of conditional survival probabilities shows that for $t > t_0$, $\mathcal{L}[X - t | X > t] = H_{0,\sigma(t),\gamma}$ with $\sigma(t) = \sigma(t_0) + \gamma(t - t_0)$. Thus for $t \geq t_0$,

$$\begin{aligned} MRL(t) &= E(X - t | X > t) = \frac{\sigma(t)}{1-\gamma} = \frac{\sigma(t_0) + \gamma(t - t_0)}{1-\gamma} \\ &= MRL(t_0) + \frac{\gamma(t - t_0)}{1-\gamma} \end{aligned}$$

■

Another consequence of the above proof is that for $t > t_0$ the quantity $(\sigma(t) - \sigma(t_0)) / (t - t_0)$ should not depend on t , as it is the case for the tail index γ . A standard method allowing to choose t_0 is to compute estimates $\hat{\sigma}(t), \hat{\gamma}(t)$ for several values of $t \geq t_0$ in the range of data and to choose t in a common stability region of the graphs $(t, \hat{\gamma}(t))$ and $(t, \frac{\hat{\sigma}(t) - \hat{\sigma}(t_0)}{t - t_0})$.

We give an example with the `rain` dataset. The following code (package `evmix`) produces the Mean Residual Life plot in Figure 2.2.3.

```
data(rain)
mrlplot(rain)
```

The stability plots for $(u, \hat{\gamma}(u))$ and $(u, \frac{\hat{\sigma}(u) - \hat{\sigma}(u_0)}{u - u_0})$ may be obtained via the command

```
tcplot(rain, tlim=c(10, 50))
```

which output is displayed in Figure 2.2.3. For this dataset, a threshold choice between $u = 25$ and $u = 40$ is reasonable.

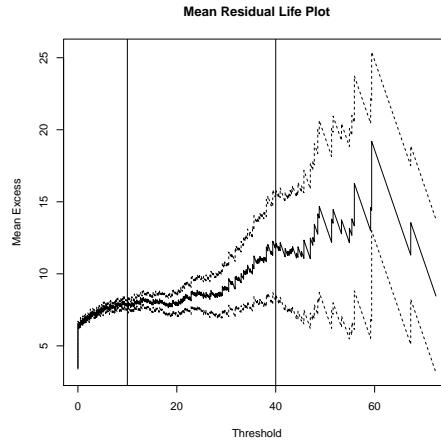


Figure 2.2: mean residual life plot for the `rain` dataset

Exercise 2.1 (Quantile estimation with simulated data):

(Recommended `R` package: `evd`.)

Generate $n = 1e + 5$ independent data $X_i, i \leq n$ from a Fréchet distribution with *c.d.f.*

$$G_{a,b,\alpha}(x) = e^{-[(x-b)/a]^{-\alpha}}$$

with $\alpha = 3, b = 1, a = 0$. In the sequel pretend that you don't know the true distribution.

1. Fit a GPD distribution above some threshold t . Choose t with a stability plot (function `tcplot`).
2. Estimate the quantile z_p of the distribution of the X_i at level $p = 1 - 5 \cdot 10^{-4}$, using a plug-in method based on the GPD model above t and an empirical estimate $\hat{\zeta}$ of $\zeta = \mathbb{P}(X_1 > t)$.
3. Investigate the variability of the quantile estimator based on a Monte-Carlo approximation. Namely repeat the experiment $N_{expe} = 100$ times (which means simulating N_{expe} datasets). For each replication i , fit a GPD model above some fixed threshold and use it to estimate a quantile \hat{z}_i . In the end, consider the empirical interquantile range (e.g. at level 0.90) of the \hat{z}_i 's. Does the true quantile belong to this interquantile range? Compute the mean squared error (based on the N_{expe} experiments) of the quantile estimate.
4. Repeat the latter question (i.e. compute the mean squared error) with a Fréchet shape $\alpha = 1.1$, and $\alpha = 10$ (you may have to change your threshold). Comment on how the shape parameter affects the mean squared error.

2.3 Regular variation of a real function

We now focus on a most useful case in terms of risk management applications in relation with very large events, that is, the case $\gamma > 0$. We shall see that the maximum domain of attraction of Fréchet type is in fact the same as the family of regularly varying (tail) distribution functions. We start with elementary definitions and first properties.

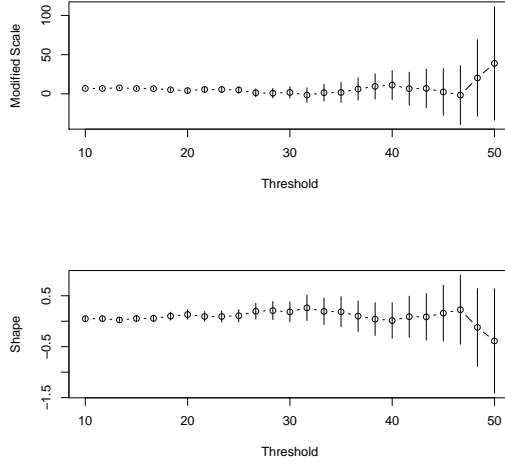


Figure 2.3: Estimates of γ and of the modified scale against the threshold.

Definition 2.3.1 (Regular variation). *A function $U : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ is regularly varying (RV) if $\exists \rho \in \mathbb{R}$ such that*

$$\forall x > 0, \lim_{t \rightarrow \infty} \frac{U(tx)}{U(t)} = x^\rho.$$

The parameter ρ is called the regular variation index. We write ' $U \in RV(\rho)$ ', meaning U is RV with regular variation index ρ . If $\rho = 0$, U is called slowly varying.

Example 2.1 (Fréchet survival function):

$U(x) = 1 - \Phi_\alpha(x) = 1 - e^{-x^{-\alpha}}$ is $RV(-\alpha)$.

Example 2.2 (Generalized Pareto):

$U(x) = (1 + \gamma x)^{-1/\gamma}$ is $RV(-1/\gamma)$.

Example 2.3 (Canonical: Pareto tail):

$U(x) = x^{-\alpha}$, $x > 1$, is $RV(-\alpha)$.

Example 2.4 (slow variation):

$U(x) = \log(1 + x)$ is slowly varying. If $\lim_{t \rightarrow \infty} f(t) = \ell \in \mathbb{R}$, then f is slowly varying, the converse is false.

Remark 2.3.2. *Remind from the last section that the max-domain of attraction condition (MDA) is equivalent to condition (2.2) concerning the tail regularity, which is*

$$\frac{1 - F(t + \sigma(t)x)}{1 - F(t)} \xrightarrow[t \nearrow x_*]{+} (1 + \gamma x)_+^{-1/\gamma}.$$

This 'resembles' a RV condition. It will be shown that it is equivalent to regular variation of $U = 1 - F$ in the case $\gamma > 0$.

Remark 2.3.3 (Equivalent formulation of RV). U is $RV(\rho) \iff \exists L$ a slowly varying function such that $U(x) = x^\rho L(x)$.

(Proof: exercise)

Proposition 2.3.4 (A sufficient condition for RV)

If $\exists h : \mathbb{R}^{+*} \rightarrow \mathbb{R}^{+*}$, measurable such that $\forall x > 0, \lim_{t \rightarrow \infty} \frac{U(tx)}{U(t)} = h(x)$ then U is RV.

Proof. (sketch of): Show that such h satisfies the Hamel equation $h(xy) = h(x)h(y)$. ■

Proposition 2.3.5 (Another sufficient condition)

If U is monotone and if $\exists (a_n)_{n \geq 0} \in \mathbb{R}$ s.t. $a_n \rightarrow +\infty$, $(\lambda_n)_{n \geq 0} > 0$ such that $\lambda_n \sim \lambda_{n+1}$ and a function $h : \mathbb{R}^{+*} \rightarrow \mathbb{R}^{+*}$ such that $\forall x > 0, \lim_n \lambda_n U(a_n x) = h(x)$ then U is RV.

Proof. Assume that U is non decreasing. Put $n(t) = \inf\{n \geq 0 : a_n \geq t\}$. Then

$$\frac{U(a_{n(t)-1}x)}{U(a_{n(t)})} \leq \frac{U(tx)}{U(t)} \leq \frac{U(a_{n(t)}x)}{U(a_{n(t)-1})},$$

and both sides of the sandwich converge to $h(x)/h(1)$. Using Proposition 2.3.4 concludes.

The proof for the non increasing case is the same, up to switching the upper and lower bounds. ■

Exercise 2.2 (Reciprocal for Proposition 2.3.5):

Let F be a cdf and assume that $(1-F) \in RV(-\alpha)$, for some $\alpha < 0$. Define $V(t) = 1/(1-F)(t)$ and let $a_n = V^{\leftarrow}(n)$. Show that

$$n(1 - F(a_n x)) \rightarrow x^{-\alpha}, \text{ for } x > 0, \text{ as } t \rightarrow \infty. \quad (2.14)$$

hint: consider the ratio $\frac{1-F(a_n x)}{1-F(a_n)}$, and derive the limit of $V(V^{\leftarrow}(n))/n$.

Exercise 2.3 (regular variation and Fréchet domain of attraction):

Let F be a c.d.f. The goal is to show the following: ‘ $(1-F)$ is regularly varying with index $-\alpha < 0$ if and only if

$$\exists (a_n)_{n \geq 0} > 0 : F^n(a_n \cdot) \rightarrow \Phi_\alpha, \quad \text{where } \Phi_\alpha(x) = e^{-x^{-\alpha}}, x > 0, \quad (2.15)$$

and to characterize the possible sequences a_n , up to tail equivalence.

1. Show that (2.15) $\Rightarrow \forall x > 0, F(x) < 1, F(a_n x) \rightarrow 1$, and $a_n \rightarrow \infty$.
2. Prove that (2.15) $\Rightarrow 1 - F$ is $RV(-\alpha)$.
3. Switching to the inverse function, show that (2.15) $\Rightarrow a_n \sim \left(\frac{1}{1-F}\right)^{\leftarrow}(n)$ as $n \rightarrow \infty$.
4. Check that if $n(1 - F(a_n x)) \rightarrow x^{-\alpha}$ for some sequence a_n , then (2.15) holds true. Check that convergence also holds for any sequence $\tilde{a}_n \sim a_n$. Conclude.

2.4 Vague convergence of Radon measures and regular variation

We now connect the notion of regular variation with convergence (in some sense) of the (rescaled) distribution of excesses. Here ‘in some sense’ turns out to be in the sense of vague convergence of measures, as defined next.

Most of the material of this section is borrowed from Resnick (1987), Chapter 3, which contains detailed proofs.

2.4.1 The space of Radon measures

In this course, the 'extreme events' will take place in a 'nice' space such as $(0, \infty)$ or $(0, \infty]$. Later on, for multivariate extremes, a very convenient space will be $\mathbf{E} = [0, \infty]^d \setminus \{\mathbf{0}\}$ where $\mathbf{0} = (0, \dots, 0)$. The reason why we include $+\infty$ (via the Alexandroff's compactification) is that it makes the intervals $[x, \infty]$, for $x > 0$ compact.

Remark 2.4.1 (Alexandroff's space). *The space $[0, \infty]$ is defined as $[0, \infty) \cup \{+\infty\}$, where $+\infty$ is an arbitrary element which is greater than any element of $[0, \infty)$. The order \leq on $[0, \infty)$ is thus extended to $[0, \infty]$. The topology on $[0, \infty]$, i.e. the family of open sets then consists of*

- All sets $V \subset [0, \infty)$ which are open sets for the usual topology (Euclidean) on \mathbb{R} .
- All sets $V \subset [0, \infty]$ such that $+\infty \in V$ and V^c is compact in $[0, \infty)$.

After having compactified $[0, \infty)$ at infinity, it is convenient to 'uncompactify' it by removing 0. We obtain the space $\mathbf{E} = (0, \infty]$. The idea behind is that we want $tx \rightarrow \infty$ as $t \rightarrow \infty$ for all $x \in \mathbf{E}$.

Exercise 2.4:

Prove that the sets $[a, \infty]$, for $a > 0$ are compact in $\mathbf{E} = (0, \infty]$.

More generally, in the remainder of this course, we consider a space \mathbf{E} which is locally compact, second countable, Hausdorff (LCSCH). Locally compact means that each point in \mathbf{E} has a compact neighborhood. Second countable means that the topology on \mathbf{E} has a countable base. Finally, Hausdorff means that for any pair $x \neq y \in \mathbf{E}$, there exists disjoint open sets U, V such that $x \in U$ and $y \in V$. In the sequel \mathbf{E} is endowed with the Borel σ -field \mathcal{E} .

Definition 2.4.2 (Radon measures).

- A measure $\mu : (\mathbf{E}, \mathcal{E}) \rightarrow [0, \infty]$ is called a Radon measure if for all compact set $K \subset \mathbf{E}$, $\mu(K) < \infty$.
- We denote $M(\mathbf{E})$ the set of all Radon measures on \mathbf{E} .
- In particular, $M(\mathbf{E})$ contains $M_p(\mathbf{E})$ the set of Radon point measures, i.e. measures of the kind $\mu = \sum_{i \in D} \delta_{x_i}$; where D is countable, and $(x_i)_{i \in D} \in \mathbf{E}$ has no accumulation point.

2.4.2 Vague topology on $M(\mathbf{E})$

Let $(\mu_n)_{n \in \mathbb{N}}, \mu \in M(\mathbf{E})$. The sequence (μ_n) converges vaguely to μ if for all function $f \in \mathcal{C}_K$ (continuous with compact support), $\int_{\mathbf{E}} f d\mu_n \rightarrow \int_{\mathbf{E}} f d\mu$. We denote $\mu_n \xrightarrow{v} \mu$. In the sequel we denote $\mu(f) := \int_{\mathbf{E}} f d\mu$. The topology associated to this notion of convergence is called the vague topology on $M(\mathbf{E})$, denoted by \mathcal{V} . It is the topology generated by the evaluation maps $T_f : \mu \mapsto \mu(f)$, for $f \in \mathcal{C}_K$. A basis for \mathcal{V} is the family of open sets

$$\left\{ V = \{ \mu \in M(\mathbf{E}) : a_i < \mu(f_i) < b_i, \quad \forall 1 \leq i \leq k \}, k \in \mathbb{N}, a_i < b_i \in \mathbb{R}, f_i \in \mathcal{C}_K \right\}.$$

It can be shown that $(M(\mathbf{E}), \mathcal{V})$ is a Polish space (separable, completely metrizable). Separable means that it contains a dense sequence; completely metrizable means that one can construct

a distance on $M(E)$ which is compatible with the topology, and for which $M(E)$ becomes a complete space.

Similarly to the case of weak convergence, we have a ‘Portmanteau theorem’

Theorem 2.4.3

The following are equivalent:

- (i) $\mu_n \xrightarrow{v} \mu$.
- (ii) $\mu_n(B) \rightarrow \mu(B)$ for all set B such that \bar{B} is compact and $\mu(\partial B) = 0$.
- (iii) For all compact $K \subset E$, $\limsup \mu_n(K) \leq \mu(K)$ and for all open set $G \subset E$, $\liminf \mu_n(G) \geq \mu(G)$.

2.4.3 Regular variation and vague convergence of tail measures

In this section $E = (0, \infty]$.

Theorem 2.4.4

Let F be a c.d.f. and $X \sim F$. The following are equivalent

- (i) F belongs to the max-domain of attraction of Φ_α (Fréchet distribution)
- (ii) $1 - F \in RV(-\alpha)$
- (iii) $\exists (a_n)_{n \geq 0} : n(1 - F(a_n x)) \xrightarrow[n \rightarrow \infty]{} x^{-\alpha}$.
- (iv) $\mu_n(\cdot) := n\mathbb{P}(\frac{X}{a_n} \in (\cdot)) \xrightarrow{v} \nu_\alpha(\cdot)$, where $\nu_\alpha[x, \infty) = x^{-\alpha}$, $x > 0$.

Proof. (ii) \iff (iii) and (ii) \implies (i) have been proven in Exercise 2.3. The fact that (i) \implies (ii) is shown in Resnick (1987), proposition 1.11 p. 54. The proof relies on Karamata’s theorem. It remains to see why (iii) \iff (iv). Assume (iv). Then for $x > 0$,

$$\begin{aligned} n(1 - F(a_n x)) &= n\mathbb{P}(X/a_n \in (x, \infty)) \\ &= \mu_n(x, \infty) \\ &\rightarrow \nu_\alpha(x, \infty) = x^{-\alpha} \quad \text{by Theorem 2.4.3 (ii),} \end{aligned}$$

which proves (iii). Now assume (iii). On order to show that (iv) holds, we need to show that for $f \in \mathcal{C}_K$, $\mu_n(f) \rightarrow \nu_\alpha(f)$. Let $f \in \mathcal{C}_K$. Let $S = \text{supp}(f) = \text{cl}\{x > 0 : f(x) > 0\}$, where $\text{cl}(A) = \bar{A}$ denotes the closure of a set A . Necessarily $0 \notin S$ otherwise S would not be closed in $(0, \infty]$. Thus $S \subset [\delta, \infty]$ for some $\delta > 0$. Introduce the probability measures P_n on $[\delta, \infty]$ defined by

$$P_n(A) = \mu_n(A) / \mu_n[\delta, \infty], \quad A \subset [\delta, \infty],$$

(which is well defined because $[\delta, \infty]$ is compact, thus $\mu_n[\delta, \infty] < \infty$).

Using (iii), for all $x > \delta$, $P_n[x, \infty] \rightarrow (x/\delta)^{-\alpha}$. Thus, using the Portmanteau theorem for probability measures, P_n converges weakly to $P = \delta^\alpha \nu(\cdot)$. Now, f has compact support in $[\delta, \infty]$ implies that f is continuous and bounded on $[\delta, \infty]$. Thus, $P_n(f) \rightarrow P(f)$, which yields $\mu_n(f) \rightarrow \mu(f)$. ■

2.4.4 Exercises

The following exercises are borrowed from Resnick (1987), chapter 3.4

Exercise 2.5:

Show that the following transformations are continuous:

1.

$$\begin{aligned} T_1 : M(E) \times M(E) &\rightarrow M(E) \\ (\mu_1, \mu_2) &\rightarrow \mu_1 + \mu_2. \end{aligned}$$

2.

$$\begin{aligned} T_1 : M(E) \times (0, \infty) &\rightarrow M(E) \\ (\mu, \lambda) &\rightarrow \lambda\mu. \end{aligned}$$

Exercise 2.6:

Let $(x_n)_{n \in \mathbb{N}}$, x in E and $c_n \leq 0, c > 0$. Show that in $M(E)$,

$$\mu_n := c_n \delta_{x_n} \xrightarrow{v} c \delta_x$$

if and only if $x_n \xrightarrow[n \rightarrow \infty]{} x$ and $c_n \xrightarrow[n \rightarrow \infty]{} c$.

Exercise 2.7:

Let $m_n = \sum_{i \in \mathbb{N}^*} n^{-1} \delta_{(\frac{i}{n})}$ and let m be the lebesgue measure on $(0, \infty)$. Show that $m_n \xrightarrow{v} m$.

2.5 Weak convergence of tail empirical measures

2.5.1 Random measures

Recall $(M(E), \mathcal{V})$ is a topological space. Thus it has a Borel σ -field $\mathcal{M}(E)$. It can be shown by monotone class arguments that $\mathcal{M}(E)$ is generated by the evaluation maps $T_f : \mu \mapsto \mu(f)$, for $f \in \mathcal{C}_K(E)$, or by the $T_F : \mu \mapsto \mu(F)$, for $F \subset E$ closed. Thus

$$\mathcal{M}(E) = \sigma\{T_f, f \in \mathcal{C}_K\} = \sigma\{T_F, F \subset E, \text{ closed}\}.$$

Given a probability space $(\Omega, \mathcal{A}, \mathbb{P})$, a random measure ξ is thus a measurable mapping $(\Omega, \mathcal{A}) \rightarrow (M(E), \mathcal{M}(E))$. A point process is a special case of such mapping, taking its value in $(M_p(E), \mathcal{M}_p(E))$, where $\mathcal{M}_p(E)$ is the trace σ -field of \mathcal{M} on M_p . The distribution of a random measure ξ is entirely determined by the 'finite dimensional distributions', *i.e.* by the laws of the random vectors $(\xi(f_1), \dots, \xi(f_k))$, where $k \in \mathbb{N}$ and $f_i \in \mathcal{C}_K, i \leq k$.

A convenient tool for characterizing the law of random measures and their convergence in distribution is the Laplace transform, defined next.

Definition 2.5.1 (Laplace transform of a random measure). *The Laplace transform of a random measure ξ is the functional*

$$\begin{aligned} \mathcal{L}_\xi : \mathcal{C}_K &\rightarrow \mathbb{R} \\ f &\mapsto \mathcal{L}_\xi(f) = \mathbb{E}\left(e^{-\xi(f)}\right) = \int_\Omega e^{-\int_E f(x)\xi(\omega, dx)} d\mathbb{P}(\omega) \end{aligned}$$

Since the law of a random vector $X \in \mathbb{R}^k$ is determined by its (usual) Laplace transform $t \mapsto \mathbb{E}\left(e^{-\langle t, X \rangle}\right)$, it is easy to see that the Laplace transform of a random measure also determines uniquely its distribution. In fact more is true: pointwise convergence of Laplace transforms of a sequence (ξ_n) determines weak convergence, as stated next.

2.5.2 Weak convergence in $M(E)$

Proposition 2.5.2 (Characterization of weak convergence)

Let $(\xi_n)_{n \in \mathbb{N}}$ be a sequence of random measures on E . The following statements are equivalent

- (i) $\xi_n \xrightarrow{w} \xi$, i.e. $\forall \phi$ bounded continuous $M(E) \rightarrow \mathbb{R}$, $\mathbb{E}(\phi(\xi_n)) \rightarrow \mathbb{E}(\phi(\xi))$.
- (ii) $\forall k \in \mathbb{N}, \forall (f_1, \dots, f_k) \in \mathcal{C}_K$, $(\xi_n(f_1), \dots, \xi_n(f_k)) \xrightarrow{w} (\xi(f_1), \dots, \xi(f_k))$.
- (iii) $\forall f \in \mathcal{C}_K$, $\mathcal{L}_{\xi_n}(f) \rightarrow \mathcal{L}_{\xi}(f)$ (pointwise convergence of the Laplace transforms)

Proof.

- (ii) \iff (iii) comes from standard properties of weak convergence in \mathbb{R}^k . Assume (ii) and fix $f \in \mathcal{C}_K$. Then letting $X_n = \xi_n(f)$ and $X = \xi(f)$, we have

$$\mathcal{L}_{\xi_n}(f) = \mathbb{E}\left(e^{-\xi_n(f)}\right) = \mathcal{L}_{X_n}(1) \rightarrow \mathcal{L}_X(1),$$

where the latter convergence comes from the fact that pointwise convergence of the Laplace transform of random variables is equivalent to their weak convergence. This proves (iii).

Conversely, assume (iii) and notice that the Laplace transform of the random vector $X_n = (\xi_n(f_1), \dots, \xi_n(f_k))$ is, for $t \in \mathbb{R}^k$,

$$\mathcal{L}_{X_n}(t) = \mathbb{E}\left(e^{-\langle t, X \rangle}\right) = \mathbb{E}\left(e^{-\sum_i t_i \xi_n(f_i)}\right) = \mathbb{E}\left(e^{-\xi_n(\sum_i t_i f_i)}\right) = \mathcal{L}_{\xi_n}\left(\sum_i t_i f_i\right).$$

Since $\sum_i t_i f_i \in \mathcal{C}_k$, the right-hand-side converges to $\mathcal{L}_{\xi}(\sum_i t_i f_i) = \mathcal{L}_X(t)$, where $X = (\xi(f_1), \dots, \xi(f_k))$ and the proof of (iii) \Rightarrow (ii) is complete.

- (i) \Rightarrow (ii) is a direct application of the continuous mapping theorem applied to the mapping $T : \mu \mapsto (\mu(f_1), \dots, \mu(f_k))$, which is continuous by definition of the vague topology.
- (ii) \Rightarrow (i) :
Assume (ii). We need to show that $(\xi_n)_{n \in \mathbb{N}}$ is (a) relatively compact (i.e. that its closure is compact for the weak topology of weak convergence in $M(E)$), and (b) the limits of any two converging subsequence coincide in distribution.

(b) is an easy exercise: it is enough to show that for two possible limits ξ^1, ξ^2 ,

$$\mathbb{P}\left(a_i < \xi^1(f_i) < b_i, 1 \leq i \leq k, a_i < b_i\right) = \mathbb{P}\left(a_i < \xi^2(f_i) < b_i, 1 \leq i \leq k, a_i < b_i\right).$$

(a) requires more care. Since $M(E)$ is a separable, metric space, the Prohorov's theorem applies (tightness implies relative compactness). It is thus enough to show that (ξ_n) is tight. To do this, use Lemma 3.20 p.153 in [Resnick \(1987\)](#): a sufficient condition is that $\xi_n(f)_{n \in \mathbb{N}}$ be tight, for all fixed $f \in \mathcal{C}_K$. Now the latter condition is satisfied because $\xi_n(f)$ converges weakly in \mathbb{R} . ■

2.5.3 Tail measure and tail empirical measure

In this section $\mathbb{E} = (0, \infty]$. Recall from Theorem 2.4.4 that for a c.d.f. F and $X \sim F$, the following equivalence:

- $1 - F$ is $RV(-\alpha)$, (i.e. $\exists (a_n)_{n \geq 0} : n(1 - F(a_n x)) \rightarrow x^{-\alpha}$)
 \iff
- $\mu_n \xrightarrow{v} \nu_\alpha$, where $\mu_n(A) = n\mathbb{P}(X/a_n \in A)$, $A \subset (0, \infty]$ and $\nu_\alpha[x, \infty] = x^{-\alpha}$, $x > 0$.

We now define the empirical version of μ_n , and we shall see that this empirical version (a random measure) converges in distribution to ν_α as well, under the same assumptions.

Definition 2.5.3 (tail empirical measure). *Let F be a c.d.f. on \mathbb{R}^+ and $X, (X_i)_{i \in \mathbb{N}} \stackrel{\text{i.i.d.}}{\sim} F$. Let $(a_n)_{n \in \mathbb{N}} > 0$ a sequence of positive numbers.*

Consider a sequence of integers $k(n)_{n \in \mathbb{N}} \in \mathbb{N}$, such that $k(n) \xrightarrow[n \rightarrow \infty]{} \infty$ and $\frac{k(n)}{n} \xrightarrow[n \rightarrow \infty]{} 0$. Write k instead of $k(n)$ for convenience. The tail empirical measure associated to F and the sequence (a_n) is the random point measure

$$\nu_{n,k} = \frac{1}{k} \sum_{i=1}^k \delta_{\left\{ \frac{X_i}{a_{\lfloor n/k \rfloor}} \right\}}$$

Proposition 2.5.4 (weak CV of the tail empirical measure)

If $F \in RV(-\alpha)$ and $(a_n)_{n \geq 0} > 0$ is such that $\mu_n \xrightarrow{v} \nu_\alpha$, then the tail empirical measures converge weakly in $M_+(\mathbb{E})$,

$$\nu_{n,k} \xrightarrow{w} \nu_\alpha.$$

Proposition 2.5.4 means that the tail empirical measure is a consistent estimator for the tail measure.

Proof. According to Proposition 2.5.2, we need to show that $\mathcal{L}_{\nu_{n,k}}(f) \rightarrow \mathcal{L}_{\delta_{\nu_\alpha}}(f) = e^{-\nu_\alpha(f)}$, for $f \in \mathcal{C}_K$.

Now, writing for a_s instead of $a_{\lfloor s \rfloor}$,

$$\begin{aligned} \mathcal{L}_{\nu_{n,k}}(f) &= \mathbb{E} \left(\exp \left\{ - \int f d\nu_{n,k} \right\} \right) \\ &= \mathbb{E} \left(\exp \left\{ - \frac{1}{k} \sum_{i \leq n} f \left(\frac{X_i}{a_{n/k}} \right) \right\} \right) \\ &= \left[\mathbb{E} \left(\exp \left\{ - \frac{1}{k} f \left(\frac{X_1}{a_{n/k}} \right) \right\} \right) \right]^n \\ &= \underbrace{\left[1 - \mathbb{E} \left(1 - \exp \left\{ - \frac{1}{k} f \left(\frac{X_1}{a_{n/k}} \right) \right\} \right) \right]}_{\mathcal{E}_{n,k}} \right]^n \end{aligned}$$

Now,

$$\begin{aligned} \mathcal{E}_{n,k} &= \int_0^\infty (1 - e^{-\frac{1}{k} f(y)}) dP_{n,k}(y) \\ &\quad (\text{where } P_{n,k} \text{ is the law of } \frac{X_i}{a_{n/k}}) \end{aligned}$$

Since f is bounded we may use a Taylor expansion of the exponential function, uniformly over x , as $k \rightarrow \infty$,

$$\sup_{x>0} \left| 1 - e^{-\frac{f(x)}{k}} - \frac{f(x)}{k} \right| = o(1/k).$$

Also $f \in \mathcal{C}_K(0, \infty]$ so that f vanishes at a neighborhood of 0, say on $(0, \delta]$ and for $0 \leq x \leq \delta$, $1 - e^{-f(x)/k} = 0$. We obtain

$$\begin{aligned} \mathcal{E}_{n,k} &= \int_{\delta}^{\infty} f(x)/k + o(1/k) dP_{n,k}(x) \\ &= n^{-1} \int_{\delta}^{\infty} (f(x) + o(1)) \frac{n}{k} dP_{n,k}(x). \end{aligned}$$

Now for $I \subset (0, \infty]$ measurable, $\frac{n}{k} P_{n,k}(I) = \frac{n}{k} \mathbb{P}(X_1 \in a_{n/k} I) = \mu_{n/k}(I)$. Vague convergence of μ_t towards ν_{α} as $t \rightarrow \infty$ entails

$$n\mathcal{E}_{n,k} \rightarrow \int_{\delta}^{\infty} f d\nu_{\alpha} = \int_0^{\infty} f d\nu_{\alpha}.$$

Finally as $n \rightarrow \infty, k \rightarrow \infty$ and $n/k \rightarrow \infty$, we obtain

$$\mathcal{L}_{\nu_{n,k}}(f) = \left(1 - \frac{n\mathcal{E}_{n,k}}{n}\right)^n \sim (1 - \nu_{\alpha}(f))^n \rightarrow e^{-\nu_{\alpha}(f)}.$$

■

2.6 Statistical applications: Hill estimator and extreme quantiles

The Hill estimator is a classical estimator of the tail index α . Many other estimators exist (Pickand's estimator, CFG estimator, ...). In this course we limit ourselves to studying the consistency of the Hill estimator. Notice that sharper results exist such as asymptotic normality or concentration inequalities under additional regularity assumptions on the tails.

The idea behind the estimator is the following: Notice first that

$$\int_1^{\infty} \nu_{\alpha}[x, \infty] x^{-1} dx = 1/\alpha.$$

The Hill estimator aims at approaching the quantity $\gamma = 1/\alpha$. The heuristic is to successively replace ν_{α} with μ_n , then a_n by a quantile, then μ_n with its empirical version $\nu_{k,n}$, as follows

$$\begin{aligned} \nu_{\alpha}(x, \infty] &\approx n(1 - F(a_n x)) = n\mathbb{P}(X/a_n > x) \\ &\approx \nu_{k,n}[x, \infty] = \frac{1}{k} \sum_{i=1}^n \mathbb{1} \left\{ \frac{X_i}{a_{\lfloor n/k \rfloor}} > x \right\} \end{aligned}$$

Now take $a_n = (1/(1-F))^{\leftarrow}(n) = F^{\leftarrow}(1-1/n)$ (see exercise 2.3 for the reason of this choice), and replace $F^{\leftarrow}(1-k/n)$ with its empirical version, which is the the k^{th} largest order statistic

$X_{(k)}$, so that $a_{\lfloor n/k \rfloor} \approx X_{(k)}$. We get

$$\begin{aligned} \frac{1}{\alpha} &= \int_1^\infty x^{-1} \nu_\alpha(x, \infty] \\ &\approx \int_1^\infty x^{-1} \frac{1}{k} \sum_{i=1}^n \mathbb{1} \left\{ \frac{X_i}{X_{(k)}} > x \right\} dx \\ &= \frac{1}{k} \sum_{i=1}^n \int_1^\infty x^{-1} \mathbb{1} \left\{ x < \frac{X_{(k)}}{X_i} \right\} dx \\ &= \frac{1}{k} \sum_{i=1}^k \log \frac{X_{(i)}}{X_{(k)}} \end{aligned}$$

N.B Here the order statistics are ranked in decreasing order, $X_{(1)} \geq X_{(2)} \geq \dots \geq X_{(n)}$.

Proposition 2.6.1 (Hill estimator)

1. Let $X, (X_i) \stackrel{\text{i.i.d.}}{\sim} F$, where $1 - F \in RV(-\alpha)$, for some $\alpha > 0$. Let $k = k(n) \xrightarrow[n \rightarrow \infty]{} \infty$ such that $k/n \xrightarrow[n \rightarrow \infty]{} 0$. The Hill estimator, defined by

$$\hat{\gamma}_n = \frac{1}{k} \sum_{i=1}^k \log \frac{X_{(i)}}{X_{(k)}}$$

is a consistent estimator of $\gamma = 1/\alpha$, i.e. it converges in probability to $1/\alpha$.

2. Under some technical second order assumptions (De Haan and Ferreira (2007), Theorem 3.2.5) $\hat{\gamma}_n$ is asymptotically normal with convergence rate k_n , and asymptotic variance γ^2 i.e.

$$\sqrt{k_n} (\hat{\gamma}_n - \gamma) \xrightarrow{w} \mathcal{N}(0, \gamma^2).$$

In the next section we shall bring more technical tools allowing to prove Proposition 2.6.1-1. In the meantime we take it for granted, show some examples, and discuss how to choose k .

As always in Extreme Value Analysis, the choice of k is a bias-variance compromise and one should choose k as small as possible such that the variance of the estimators remains reasonable. Also k should be chosen in a region where the estimated quantity is relatively robust to a small variation of k , i.e. in a stability region of the estimate. A common practice is to draw a Hill-plot and choose k within such a stability region, provided it exists. The three graphs in Figure 2.4 show such Hill plots obtained with $n = 1e + 4$ Fréchet distributed data with distribution $G(x) = e^{-[(x-b)/a]^{-\alpha}}$ with $\alpha = 1, a = 1$ and $b = 0, 5, 10$. The horizontal line is the true tail index $\gamma = 1/\alpha = 1$. The yellow lines are the asymptotic Gaussian confidence intervals (at level 0.9) based on Proposition 2.6.1-2. Even though a stability region indeed exists for $b = 0$ (between $k \in \{300, \dots, 1500\}$ say), it is reduced for $b = 5$ to $k \in \{400, \dots, 600\}$ and it vanishes for $b = 10$, which is an example of ‘Hill horror plot’, i.e. a case where the Hill estimator is not well behaved. This example shows in particular that the Hill estimator is not invariant under translation $X_i \mapsto X_i + b$, for some $b > 0$.

We now present some applications to extreme quantile estimation.

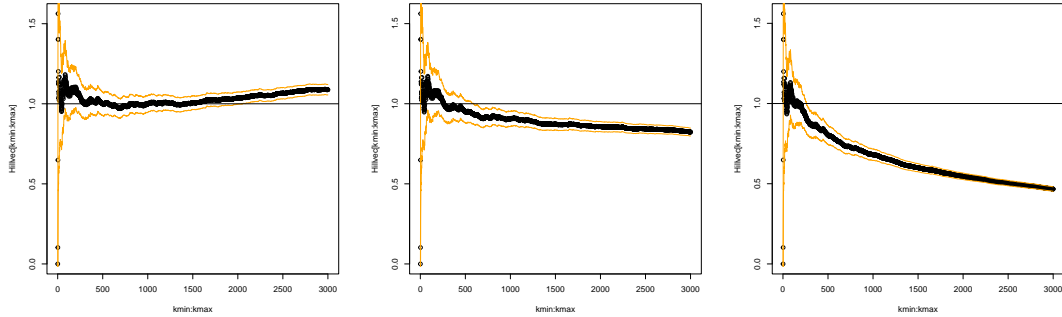


Figure 2.4: Hill plots, for three shifted distributions with identical scale and tail index

2.6.1 Estimation of extreme quantiles based on the tail index alone

Consider the heavy-tailed case, *i.e.* the setting of Theorem 2.4.4. As an alternative to the plug-in estimation of a high quantile of order $p \ll 1$ based on inverting a (fitted) GPD or GEV distribution function, the method presented next only involves estimation of $\alpha > 0$ (or $\gamma = 1/\alpha > 0$).

Consider the function $U = (1/(1 - F))^\leftarrow$ and notice that $1 - F \in RV(-\alpha) \iff U \in RV(1/\alpha)$, by combining Proposition 2.4.4-(iii), Lemma 1.2.5 and Proposition 2.3.5. Thus

$$\frac{U(ty)}{U(t)} \xrightarrow[t \rightarrow \infty]{} y^{1/\alpha}. \quad (2.16)$$

Our goal here is to estimate $U(1/p)$ based on the asymptotic approximation $\frac{U(ty)}{U(t)} \approx y^{1/\alpha}$ given by (2.16). Choose k large enough, such that $p < k/n \ll 1$. Then with $t = n/k$, a natural estimate of $U(t) = U(n/k)$ is $X_{(k)}$, the k^{th} (largest) order statistic of the sample. We then choose y such that $ty = 1/p$, *i.e.* $y = k/(np)$. We obtain the approximation

$$\frac{U(1/p)}{U(n/k)} \approx \left(\frac{k}{np}\right)^{\frac{1}{\alpha}}.$$

Replacing unknown quantity with empirical ones,

$$\hat{z}_{p,w} = \widehat{U(1/p)} = X_{(k)} \left(\frac{k}{np}\right)^{\hat{\gamma}}, \quad (2.17)$$

where $\hat{\gamma}$ is a consistent estimator of the tail index (e.g. the Hill estimator) constructed with an *i.i.d.* sample $(X_i)_{i \leq n} \sim F$. The above estimator is called the ‘Weissman estimator’ and its statistical properties have been the subject of extensive research.

2.6.2 More on regular variation

Karamata’s theorem The main missing piece for the proof of the consistency of the Hill estimator is Karamata’s theorem, a major tool in one-dimensional EVT.

Idea: For integration purposes (of the kind $\int_x^\infty U(t)dt$ or $\int_0^x U(t)dt$), If U is $RV(\rho)$ then it behaves as $t \mapsto t^\rho$ would, as $x \rightarrow \infty$. More precisely,

- if $U(t) = t^\rho$ and $\rho < -1$, $\int_x^\infty U(t)dt = -(\rho + 1)^{-1}x^{\rho+1} = -(\rho + 1)^{-1}xU(x)$.
- if $U(t) = t^\rho$ and $\rho > -1$, $\int_0^x U(t)dt = (\rho + 1)^{-1}x^{\rho+1} = (\rho + 1)^{-1}xU(x)$.

Karamata's theorem says that the same is true as $x \rightarrow \infty$ when $U \in RV(\rho)$.

Theorem 2.6.2 (Karamata)

Let $U : \mathbb{R}^+ \mapsto \mathbb{R}^+$ be a $RV(\rho)$ function, s.t. $\int_0^x U < \infty \forall x > 0$.

1. If $\rho \geq -1$ then $x \mapsto \int_0^x U$ is $RV(\rho + 1)$ and

$$\lim_{x \rightarrow \infty} \frac{xU(x)}{\int_0^x U} = \rho + 1. \quad (2.18)$$

Conversely if (2.18) then $U \in RV(\rho)$.

2. If $\rho < -1$ or if $\rho = 1$ and $\int_1^\infty U < \infty$ then $x \mapsto \int_x^\infty U$ is $RV(\rho + 1)$ and

$$\lim_{x \rightarrow \infty} \frac{xU(x)}{\int_x^\infty U} = -\rho - 1. \quad (2.19)$$

Conversely if (2.19) then $U \in RV(\rho)$.

Proof. See Resnick (1987), p. 17 or Resnick (2007), p. 25. ■

Corollary 2.6.3 (Karamata representation)

A function $L : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ is slowly varying if and only if

- $\exists c : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ such that $\lim_\infty c(x) = c \in (0, \infty)$, and
- $\exists \epsilon : \mathbb{R}^+ \rightarrow \mathbb{R}^+$ such that $\lim_\infty \epsilon(x) = 0$,

such that

$$L(x) = c(x) \exp \left(\int_1^x \frac{\epsilon(t)}{t} dt \right). \quad (2.20)$$

Proof. The proof of the sufficiency of (2.20) is an easy exercise. For the converse, let $L \in RV(0)$. From Karamata theorem, we have

$$b(x) := \frac{xL(x)}{\int_0^x L} \rightarrow 1 \quad \text{as } x \rightarrow \infty.$$

By definition of b we may write

$$L(x) = \frac{b(x)}{x} \int_0^x L = b(x) \exp \left\{ \log \frac{\int_0^x L}{x} \right\} \quad (2.21)$$

But also

$$\begin{aligned} \log \frac{\int_0^x L}{x} &= \int_1^x \frac{d}{dt} \left[\log \left(\int_0^t L \right) - \log t \right] dt + D \quad (D : \text{a constant}) \\ &= \int_1^x \left(\frac{L(t)}{\int_0^t L} - \frac{1}{t} \right) dt + D \quad (D : \text{a constant}) \\ &= \int_1^x \frac{b(t) - 1}{t} dt + D \end{aligned}$$

Setting $\epsilon(t) = b(t) - 1$, we have $\epsilon(t) \rightarrow 0$ and the latter display combined with (2.21) yields

$$L(x) = \underbrace{b(x)e^D}_{:=c(x) \rightarrow e^D > 0} \exp \left\{ \int_1^x \frac{\epsilon(t)}{t} dt \right\},$$

which concludes the proof. ■

Corollary 2.6.4 (Karamata representation of RV functions)

$U \in RV(\rho) \iff U(x) = c(x) \exp \int_1^x \alpha(t)/t dt$, for some functions $c(x) \rightarrow c > 0$ and $\alpha(t) \rightarrow \rho$.

Proof.

$$\begin{aligned} U \in RV(\rho) &\iff U(x) = L(x)x^\rho \\ &\iff U(x) = c(x) \exp \left(\int_1^x \epsilon(t)/t dt \right) \exp(\rho \log x) \quad (\text{Corollary 2.6.3}) \\ &\iff U(x) = c(x) \exp \left(\int_1^x [\epsilon(t) + \rho]/t dt \right). \end{aligned}$$
■

2.6.3 Back to the Hill estimator: proof of consistency

The proof follows the lines from Resnick (2007). Remind that $a(t) = a_{[t]}$. To alleviate notations, we denote

$$\begin{aligned} \nu_n &= \frac{1}{k} \sum_{i=1}^k \delta_{\left\{ \frac{X_i}{a(n/k)} \right\}} \quad (= \nu_{n,k}) \\ \hat{\nu}_n &= \frac{1}{k} \sum_{i=1}^k \delta_{\left\{ \frac{X_i}{\bar{X}_{(k)}} \right\}} \end{aligned}$$

According to the arguments leading to the statement, $\widehat{1/\alpha}_n = \int_1^\infty x^{-1} \hat{\nu}_n[x, \infty] dx$ and $1/\alpha = \int_1^\infty x^{-1} \nu_\alpha[x, \infty] dx$. We need to show that

$$\int_1^\infty x^{-1} \hat{\nu}_n[x, \infty] dx \xrightarrow[n \rightarrow \infty]{P} \int_1^\infty x^{-1} \nu_\alpha[x, \infty] dx. \quad (2.22)$$

1. Behavior of the order statistics

We show that

$$\frac{X_{(k)}}{a(n/k)} \xrightarrow{P} 1. \quad (2.23)$$

Indeed for $\epsilon > 0$,

$$\begin{aligned} \mathbb{P} \left(\left| \frac{X_{(k)}}{a(n/k)} - 1 \right| > \epsilon \right) &= \mathbb{P} \left(\frac{X_{(k)}}{a(n/k)} > 1 + \epsilon \right) + \mathbb{P} \left(\frac{X_{(k)}}{a(n/k)} < 1 - \epsilon \right) \\ &= \mathbb{P} \left(\frac{1}{k} \sum_{i=1}^n \delta_{\frac{X_i}{a(n/k)}}(1 + \epsilon, \infty) > 1 \right) + \mathbb{P} \left(\frac{1}{k} \sum_{i=1}^n \delta_{\frac{X_i}{a(n/k)}}(1 - \epsilon, \infty) < 1 \right) \\ &= \mathbb{P}(\nu_n(1 + \epsilon, \infty] > 1) + \mathbb{P}(\nu_n(1 - \epsilon, \infty) < 1] \end{aligned}$$

Now, Proposition 2.5.4 implies that $\nu_n(1 + \epsilon, \infty] \xrightarrow{P} (1 + \epsilon)^{-\alpha} < 1$ and $\nu_n(1 - \epsilon, \infty] \xrightarrow{P} (1 - \epsilon)^{-\alpha} < 1$. Whence, the latter display converges to zero and (2.23) is proved.

2. Convergence of $\hat{\nu}_n$ in probability in $M_+(0, \infty]$

Notice first that

$$\hat{\nu}_n(\cdot) = \nu_n\left(\frac{X_{(k)}}{a(n/k)} \cdot\right).$$

Consider the operator

$$\begin{aligned} T : M(0, \infty] \times \mathbb{R}_+^* &\rightarrow M(0, \infty] \\ (\mu, x) &\mapsto \mu(x \cdot). \end{aligned}$$

Then $\hat{\nu}_n = T\left(\nu_n, \frac{X_{(k)}}{a(n/k)}\right)$. It can be shown (See [Resnick \(2007\)](#), p. 83) that T is continuous at (ν_α, x) for $x > 0$ (see [Resnick \(2007\)](#) p. 84). Then (2.23) combined with the continuous mapping theorem yields

$$\hat{\nu}_n \xrightarrow{P} \nu_\alpha \quad \text{in } M(0, \infty]. \quad (2.24)$$

3. Convergence of $\int_1^\infty x^{-1} \hat{\nu}_n[x, \infty] dx$ We are ready to prove (2.22). For $M > 0$, (2.22) is equivalent to

$$\underbrace{\int_1^M x^{-1} \hat{\nu}_n[x, \infty] dx}_{A_{M,n}} + \underbrace{\int_M^\infty x^{-1} \hat{\nu}_n[x, \infty] dx}_{B_{M,n}} \xrightarrow{P} \underbrace{\int_1^M x^{-1} \nu_\alpha[x, \infty] dx}_{A_M} + \underbrace{\int_M^\infty x^{-1} \nu_\alpha[x, \infty] dx}_{B_M} \quad (2.25)$$

- For any fixed $M > 0$, the mapping $\mu \mapsto \int_1^M x^{-1} \mu[x, \infty] dx$ is continuous on $M(0, \infty]$. To see this, notice that the integrand is a decreasing function of x , so that the integral can be framed between Riemann sums. In addition, $\mu_n \xrightarrow{v} \mu$ implies that for fixed $x > 0$ which is not an atom of μ , $\mu_n[x, \infty] \rightarrow \mu[x, \infty]$.
- The continuous mapping theorem combined with (2.24) thus implies that $A_{M,n} \xrightarrow{P} A_M$, for any fixed M .
- Since $\lim_{M \rightarrow \infty} B_M = 0$, it is enough to show that for any $\epsilon > 0$, $\exists M_0 > 1$ such that $\forall M \geq M_0$,

$$\lim_n \mathbb{P}(B_{M,n} > \epsilon) \leq \delta. \quad (2.26)$$

Let $M > 1$ and $\eta > 0$. We have

$$\mathbb{P}(B_{M,n} > \epsilon) = \underbrace{\mathbb{P}\left(B_{M,n} > \epsilon, \left|\frac{X_{(k)}}{a(n/k)} - 1\right| > \eta\right)}_{p_{n,M}^1} + \underbrace{\mathbb{P}\left(B_{M,n} > \epsilon, \left|\frac{X_{(k)}}{a(n/k)} - 1\right| \leq \eta\right)}_{p_{n,M}^2}.$$

From (2.23), $p_{n,M}^1 \leq \mathbb{P}\left(\left|\frac{X_{(k)}}{a(n/k)} - 1\right| > \eta\right) \rightarrow 0$ as $n \rightarrow \infty$. Also ,

$$\begin{aligned}
p_{n,M}^2 &= \mathbb{P}\left(\int_M^\infty x^{-1} \nu_n \left[\frac{X_{(k)}}{a(n/k)} x, \infty\right] dx > \epsilon, \left|\frac{X_{(k)}}{a(n/k)} - 1\right| \leq \eta\right) \\
&\leq \mathbb{P}\left(\int_M^\infty x^{-1} \nu_n [(1-\eta)x, \infty] dx > \epsilon\right) \\
&= \mathbb{P}\left(\int_{M(1-\eta)}^\infty y^{-1} \nu_n [y, \infty] dy > \epsilon\right) \\
&\stackrel{\text{Markov}}{\leq} \frac{1}{\epsilon} \mathbb{E}\left(\int_{M(1-\eta)}^\infty x^{-1} \nu_n [x, \infty] dx\right) \\
&= \frac{1}{\epsilon} \int_{M(1-\eta)}^\infty x^{-1} \frac{n}{k} (1-F)(a(n/k)x) dx \\
&= \frac{1}{\epsilon} \frac{n}{k} \int_{M(1-\eta)a(n/k)}^\infty \underbrace{x^{-1} (1-F)(x)}_{U(x)} dx
\end{aligned}$$

The function U in the latter integrand is $RV(-\alpha - 1)$, so Karamata theorem implies that $\int_T^\infty U \sim TU(T)/\alpha$, with $TU(T) = (1-F)(T)$, *i.e.*

$$\begin{aligned}
\frac{1}{\epsilon} \frac{n}{k} \int_{M(1-\eta)a(n/k)}^\infty x^{-1} (1-F)(x) dx &\sim_{n \rightarrow \infty} \frac{1}{\epsilon} \frac{n}{k} (1-F)\left(M(1-\eta)a(n/k)\right) \\
&\xrightarrow{n \rightarrow \infty} \frac{1}{\epsilon} \nu_\alpha [M(1-\eta), \infty] \\
&= \frac{1}{\epsilon} (M(1-\eta))^{-\alpha}
\end{aligned}$$

Choosing M_0 large enough so that the latter quantity is less than $\delta/2$ for $M = M_0$ shows (2.26) and concludes the proof.

Chapter 3

Multivariate Extremes

In this chapter, the multivariate extensions of ideas from univariate EVT are exposed. In particular the possible limiting distribution for maxima of multivariate samples are derived, and equivalent formulations in terms of limiting distributions of excesses are stated. Multivariate regular variation plays a central role when considering such multivariate ‘excesses above large thresholds’.

Notations The usual order relation \leq on \mathbb{R} is extended to a partial order \preceq on \mathbb{R}^d : $a \preceq b$ means $\forall j \in \{1, \dots, d\}, a_j \leq b_j$. Similarly $a \prec b$ means $a_j \prec b_j$ for all $j \leq d$. For $a \preceq b$, the ‘rectangle’ $[a, b]$ is the product $\prod_{i=1}^d [a_i, b_i]$. Binary operations are understood componentwise, e.g. $\vee(a, b) = (\vee(a_1, b_1), \vee(a_2, b_2), \dots, \vee(a_d, b_d))$. If $(X_n)_{n \geq 0}$ is an *i.i.d.* sample $\Omega \rightarrow \mathbb{R}^d$ we denote $X_i^{(j)}$ the j^{th} component of X_i .

3.1 Limit distributions of maxima

Let $X, X_1, \dots, X_n \stackrel{i.i.d.}{\sim} F$, where F is a multivariate *c.d.f.* $\mathbb{R}^d \rightarrow \mathbb{R}^+$ and $X = (X^{(1)}, \dots, X^{(d)})$ is a d -variate random vector. The basic assumption in multivariate EVT (MEVT) is that $\exists(a_n = (a_{1,n}, \dots, a_{d,n}))_{n \in \mathbb{N}} \succ 0, \exists(b_n = (b_{1,n}, \dots, b_{d,n}))_{n \in \mathbb{N}} \in \mathbb{R}^d, \exists Z$ a non-degenerate r.v., such that

$$\frac{\bigvee_{i=1}^n X_i - b_n}{a_n} \xrightarrow{w} Z. \quad (3.1)$$

An equivalent statement in terms of distribution is that $\exists G$ an non-degenerate *c.d.f.* on \mathbb{R}^d , such that

$$F^n(a_n \cdot + b_n) \xrightarrow{w} G(\cdot). \quad (3.2)$$

Any such limit G is called a **Multivariate extreme value distribution** (MEVD).

3.1.1 Max-stability

Definition 3.1.1. A *c.d.f.* $G : \mathbb{R}^d \rightarrow [0, 1]$ is called **max-stable** if $\forall t > 0, \exists \alpha(t) \succ 0, \exists \beta(t) \in \mathbb{R}^d$:

$$G(x) = G^t(\alpha(t)x + \beta(t)). \quad (3.3)$$

A non-degenerate random variable Z is called max-stable if its distribution function is.

Remark 3.1.2. If (3.3) holds true for $t \in \mathbb{N}$, then it also holds for rational t 's, thus also for every positive real t . Thus, a non-degenerate random variable Z is max-stable if and only if for an i.i.d. sample $(Z_n)_{n \geq 1} \sim Z$, $\forall n \in \mathbb{N}^*$, $\exists \alpha(n) \succ 0$, $\exists \beta(n) \in \mathbb{R}^d$:

$$\frac{\bigvee_{i=1}^n Z_i - \beta(n)}{\alpha(n)} \stackrel{d}{=} Z \quad (3.4)$$

Proposition 3.1.3

A non-degenerate multivariate c.d.f. is a MEVD if and only if it is max-stable.

Proof. The fact that a max-stable distribution is a MEVD one is immediate: take $a_n = \alpha(n)$, $b_n = \beta(n)$, then (3.2) holds since the right-hand side and the left-hand side are equal for all n . For the converse statement, notice first that multivariate weak convergence (3.2) entails weak convergence of the margins (to see this, apply (3.2) to $\mathbf{x} = (\infty, \infty, \dots, x, \infty, \dots)$). The arguments in the proof of Proposition 1.3.2 show that for all $1 \leq j \leq d$ and $t > 0$,

$$\exists \alpha_j(t) > 0, \exists \beta_j(t) : \frac{a_{j, \lfloor nt \rfloor}}{a_{j, n}} \xrightarrow{n \rightarrow \infty} \alpha_j(t) ; \frac{b_{j, \lfloor nt \rfloor} - b_{j, n}}{a_{j, n}} \xrightarrow{n \rightarrow \infty} \beta_j(t).$$

Define $\alpha(t) = (\alpha_1(t), \dots, \alpha_d(t))$ and $\beta(t)$ similarly. On the one hand, for all $x \in \mathbb{R}^d$, we have

$$F^{\lfloor nt \rfloor}(a_n x + b_n) \xrightarrow{n \rightarrow \infty} G(x)^t. \quad (3.5)$$

On the other hand, write

$$a_n x + b_n = a_{\lfloor nt \rfloor} \underbrace{\left(\frac{a_n}{a_{\lfloor nt \rfloor}} \left(x - \frac{(b_{\lfloor nt \rfloor} - b_n)}{a_n} \right) \right)}_{=y_n} + b_{\lfloor nt \rfloor}.$$

Notice that $y_n \xrightarrow{n \rightarrow \infty} \frac{x - \beta(t)}{\alpha(t)} := y$. Thus

$$F^{\lfloor nt \rfloor}(a_n x + b_n) = F^{\lfloor nt \rfloor}(a_{\lfloor nt \rfloor} y_n + b_{\lfloor nt \rfloor}) \xrightarrow{n \rightarrow \infty} G(y)$$

where the latter convergence is easily proved using $y_n \rightarrow y$ and the continuity of the limit G at y . The latter display combined with (3.5) shows that $G^t(x) = G\left(\frac{x - \beta(t)}{\alpha(t)}\right)$. ■

3.1.2 Max infinite divisibility

Definition 3.1.4. A c.d.f. F on \mathbb{R}^d is called *max-infinitely divisible* (max-id) if $\forall t > 0$, F^t is a distribution function on \mathbb{R}^d .

Remark 3.1.5. 1. A function $H : \mathbb{R}^d \rightarrow [0, 1]$ 'is a c.d.f.' if it is the distribution function of a probability measure on \mathbb{R}^d . This is the case if and only if the following conditions are satisfied

- (a) $\lim_{x_i \rightarrow -\infty} H(x_1, \dots, x_i, \dots, x_d) = 0$, $\forall i \leq d, \forall (x_j)_{j \neq i} \in \mathbb{R}^{d-1}$.
- (b) $\lim_{x_1, \dots, x_d \rightarrow +\infty} H(x_1, \dots, x_d) = 1$
- (c) $\forall j \leq d, x_j \mapsto H(x_1, \dots, x_j, \dots, x_d)$ is right-continuous.

(d) For $a \preceq b$, denoting for $\beta \subset \{1, \dots, d\}$, $x_{\beta, j} \begin{cases} a_j & \text{if } j \in \beta \\ b_j & \text{if } j \in \{1, \dots, d\} \setminus \beta \end{cases}$, it holds that

$$H\{(a, b)\} := \sum_{\beta \subset \{1, \dots, d\}} (-1)^{|\beta|} H(x_\beta) \geq 0.$$

Thus, if F is a multivariate c.d.f. then F^t is a c.d.f. if and only if condition (d) is satisfied for F^t .

2. If $d = 1$ and F is a c.d.f. then F^t is a c.d.f. for all $t > 0$. Thus every univariate c.d.f. is max-id.
3. Every max-stable distribution is max-id

Exercise 3.1:

Are the c.d.f.'s F associated with the following probability distributions P max-id ?

1. in \mathbb{R}^d , $P = \delta_a$ for some $a \in \mathbb{R}^d$.
2. in \mathbb{R}^2 , $P = \frac{1}{2} (\delta_{(1,0)} + \delta_{(0,1)})$
3. in \mathbb{R}^2 , $P = \frac{1}{2} (\delta_{(0,0)} + \delta_{(1,1)})$

3.1.3 Characterizing Max-ID distributions

To begin with, we give an example of construction of max-id distribution. We shall prove later on that every max-id distribution can be represented this way.

Canonical example Let $\ell \in \mathbb{R}^d$ and let $E = [\ell, \infty] \setminus \{\ell\}$ the compactified orthant deprived from its 'origin' ℓ . In the sequel we need the following definition. Recall that point processes are special cases of random measures taking value in $M_p(E)$.

Definition 3.1.6 (Poisson process). *A point process $N = \sum_{i \geq 1} \delta_{X_i}$ on a LCSCH space E is a Poisson process if and only if there is a Radon measure λ on E such that for all disjoint, measurable sets (C_1, \dots, C_k) in E ,*

1. $(N(C_1), \dots, N(C_k))$ is a random vector
2. the random variables $N(C_i)_{i \leq k}$ are independent
3. $N(C_i) \sim \text{Poisson}(\lambda(C_i))$

The measure λ is called the intensity measure of N and we write $N \sim PP(\lambda)$ (PP stands for 'Poisson Process').

Let μ be a Radon measure on (E, \mathcal{E}) . Consider the product space $E' = \mathbb{R}^+ \times E$. Define a Radon measure on E' as the product measure Lebesgue $\otimes \mu$, that is

$$\lambda((t_1, t_2) \times A) = (t_2 - t_1)\mu(A), \quad A \in \mathcal{E}, t_1 \leq t_2.$$

Let $N \sim PP(\lambda)$. Then one may write $N = \sum_{n \geq 0} \delta_{(t_n, Z_n)}$, where $t_n \in \mathbb{R}^+$ and $Z_n \in E$. For $t > 0$ consider the random variable

$$Y(t) = \left(\bigvee_{\{k: t_k < t\}} Z_k \right) \vee \ell.$$

Let F_t denote the distribution function of $Y(t)$. We shall show that $F_t = F_1^t$, thus F_1 will be proved to be a max-id distribution on \mathbb{R}^d , provided $Y(1)$ is indeed real valued with probability 1. By definition of F_t , we have for $x \not\geq \ell$, $F_t(x) = 0$ and for $x \succeq \ell$,

$$\begin{aligned} F_t(x) &= \mathbb{P} \left(\bigvee_{k: t_k \leq t} Z_k \preceq x \right) \\ &= \mathbb{P} (N([0, t] \times [\ell, x]^c) = 0) \\ &= \exp\{-\lambda([0, t] \times [\ell, x]^c)\} \\ &= e^{-t\mu([\ell, x]^c)}, \end{aligned}$$

where $[\ell, x]^c = E \setminus [\ell, x] \subset E$.

In particular $F_1(x) = e^{-\mu[\ell, x]^c}$ and we indeed have $F_t = F_1^t$. To make sure that $Y(1) \in \mathbb{R}^d$ with probability 1, we need to ensure that

1. $F_1(x) \xrightarrow{x \rightarrow +\infty} 1$, i.e. $\mu[\ell, x]^c \rightarrow 0$ as $x \rightarrow \infty$ in \mathbb{R}^d ,
2. $F_1(x) \xrightarrow{x_j \rightarrow -\infty} 0$ for all $j \leq d$,

This is the case if and only if μ is such that

$$\begin{cases} \mu \left[\bigcup_{j=1}^d \{x_j = +\infty\} \right] = 0 & (\text{'}\mu \text{ puts no mass on lines at infinity' }) & (3.6a) \\ \ell \succ \infty \text{ or } \mu[\ell, x]^c \xrightarrow{x \searrow \ell} +\infty & (\text{explosion at the origin}) & (3.6b) \end{cases}$$

Every Radon measure μ satisfying (3.6a) and (3.6b) thus gives rise to a max-id distribution function $F(x) = e^{-\mu[\ell, x]^c}$ on \mathbb{R}^d . In fact, every max-id distribution is of this kind, as shown next.

Proposition 3.1.7 (characterization of max-id distributions)

Let F be a non degenerate c.d.f. on \mathbb{R}^d and let $Y \sim F$. Then F is max-id if and only if $\exists \ell \in [-\infty, \infty]^d \setminus \{\infty\}$, $\exists \mu$ a Radon measure on $E = [\ell, \infty] \setminus \ell$, satisfying 3.6a and 3.6b, such that

$$F(x) = \begin{cases} 0 & \text{if } \ell \not\leq x \\ e^{-\mu[\ell, x]^c} & \text{if } \ell \leq x. \end{cases} \quad (3.7)$$

In such a case, $\exists N = \sum_{k \geq 0} \delta_{(t_k, Z_k)}$ a Poisson Process on $E' = \mathbb{R}^+ \times E$ with intensity measure $\lambda = \text{Lebesgue} \otimes \mu$, such that

$$Y \stackrel{d}{=} \left(\max_{k: t_k \leq 1} Z_k \right) \vee \ell,$$

with the convention that $\bigvee_{k \in \emptyset} Z_k = -\infty$.

sketch of proof. The sufficiency has been shown in the argument before the statement. Conversely, let F be max-id. We need to show that

1. The set $R = \{x \in [-\infty, \infty]^d : F(x) > 0\}$ is a rectangle of the kind $\prod_{j=1}^d R_j$ with $R_j = (\ell_j, \infty]$ or $R_j = [\ell_j, \infty]$ for some $\ell_j \in [-\infty, \infty)$.
2. There exists a Radon measure μ on $[-\infty, \infty]^d$ satisfying 3.6a, 3.6b such that

$$\begin{cases} \mu[\ell, x]^c = -\log F(x) & (x \succeq \ell) \\ \mu[-\infty, \infty]^d \setminus [\ell, \infty)^d = 0. \end{cases} \quad (3.8)$$

1. Define $R_j = \{x \in [-\infty, \infty] : F_j(x) > 0\}$. We want to show that $R = \prod_{j=1}^d R_j$. First, if $x \in R$ then for all j $F_j(x_j) > 0$ thus $x \in \prod R_j$. To prove the converse inclusion, let $x \in \prod R_j$. We need to show that $x \in R$. For all $i \leq d$ it holds that $F_i(x_i) > 0$, whence $\exists \mathbf{y}_i \in R$ such that $x_i = \pi_i(\mathbf{y}_i)$. Define $\mathbf{y} = \bigwedge_{j=1}^d \mathbf{y}_j$. By construction, $\pi_i(\mathbf{y}) \leq \pi_i(\mathbf{y}_i) = x_i$ for all i , thus $\mathbf{y} \preceq x$. It remains to show that (i) $\mathbf{y} \in R$, and that (ii) ($\mathbf{y} \in R, \mathbf{y} \preceq x \Rightarrow x \in R$). Claim (ii) derives immediately from the fact that F is non-decreasing along each coordinate. As for claim (i), since $\mathbf{y}_i \in R$ for all i , it is enough to show that for $y, z \in R$, we have $y \wedge z \in R$. To do so, we use the fact that for any distribution function H , by a union bound on the event $Z \not\leq (y \wedge z)$ where $Z \sim H$, we have

$$1 - H(y \wedge z) \leq (1 - H(y)) + (1 - H(z)).$$

Since F is max-id, $F^{1/n}$ is a distribution function for all n , so that the previous display yields

$$n(1 - F^{1/n}(y \wedge z)) \leq n(1 - F^{1/n}(y)) + n(1 - F^{1/n}(z)).$$

Taking the limit as $n \rightarrow \infty$ we obtain

$$-\log F(y \wedge z) \leq -\log F(y) - \log F(z)$$

thus

$$F(y \wedge z) \geq F(y)F(z).$$

Finally, if $y, z \in R$ then $F(y) > 0$ and $F(z) > 0$. The previous display implies $F(y \wedge z) > 0$, i.e. $y \wedge z \in R$, which concludes the proof of (1).

2. We shall obtain μ as a vague limit of rescaled versions of the probability distributions P_t associated with F^t . Define $\mu_n = nP_{1/n}$. We show that μ_n is relatively compact and that the limits of two subsequences must coincide.

- for $x \succ \ell$, denoting $[\ell, x]^c = [\ell, \infty] \setminus [\ell, x]$, we have

$$\begin{aligned} \mu_n[\ell, x]^c &= n(1 - F(x)^{1/n}) \\ &= n(1 - e^{1/n \log F(x)}) \sim_{n \rightarrow \infty} n(-1/n \log F(x)) \\ &\xrightarrow[n \rightarrow \infty]{} -\log F(x) \end{aligned}$$

Thus two limits of any two subsequences must coincide on the sets $[\ell, \infty]^c$, which generate the Borel σ -field \mathcal{E} on E , so that they coincide everywhere.

- As for sequential compactness, it is enough to show that for all compact set K in $E = [\ell, \infty] \setminus \{\ell\}$, $\sup_n \mu_n(K) < \infty$. But for such K , we have $K \subset [\ell, \infty] \setminus [\ell, \delta]$ for some $\delta \succ \ell$. Thus $\sup_n \mu_n(K) \leq \sup_n \mu_n([\ell, \infty] \setminus [\ell, \delta]) < \infty$ since $\mu_n([\ell, \infty] \setminus [\ell, \delta]) \rightarrow -\log F(\delta) < \infty$.

■

Exercise 3.2 (Resnick (1987), chap. 5: dependence structures):

1. Let F be max-id on \mathbb{R}^d with exponent measure μ . Show that F is a product $F(x) = \prod_{j=1}^d F_j(x_j) \iff \mu$ concentrates on the translated axes $\mathcal{C}_j = \{\ell_j + te_j, t \geq 0\}$, where e_j is the j^{th} canonical basis vector.
2. Let Y with max-id distribution in \mathbb{R}^4 with exponent measure μ . Give necessary and sufficient conditions on μ for (Y_1, Y_2) to be independent from (Y_3, Y_4) .
3. Give an example of exponent measure in \mathbb{R}^3 such that $\mu(\ell, \infty]^3 = 0$ but no Y_i is independent from the complementary pair (for $Y \sim F$ with exponent measure μ).

3.2 Characterization of simple max-stable distributions

3.2.1 Reduction to the standard case

Since max-stable distributions are in particular max-id, we already know that any max-stable distribution G writes $G(x) = e^{-\mu[\ell, x]^c} \mathbb{1}_{x \succeq \ell}$ for some $\ell \in [-\infty, \infty)^d$ and some Radon measure μ satisfying 3.6a and 3.6b. More structure can be obtained when G has ‘standard’ margins, *i.e.* unit Fréchet margins

Definition 3.2.1 (Simple max-stable vector/distribution). $Z : \Omega \rightarrow \mathbb{R}^d$ is ‘simple max-stable’ if

1. For all $j \in \{1, \dots, d\}$: $Z^{(j)} \sim \Phi_1$, *i.e.* $\mathbb{P}(Z^{(j)} \leq x) = e^{-1/x}, x > 0$, and
2. $\frac{1}{n} \bigvee_{i=1}^n Z_i \stackrel{d}{=} Z_1$, for $(Z_i)_{i \in \mathbb{N}} \stackrel{\text{i.i.d.}}{\sim} Z$.

Proposition 3.2.2 (Standardizing max-stable distribution)

Let Z be a non-degenerate random vector. Then Z is a max-stable vector with normalizing sequences (a_n, b_n) such that $\frac{\bigvee Z_i - b_n}{a_n} \stackrel{d}{=} Z$ for $Z_i \stackrel{\text{i.i.d.}}{\sim} Z$, if and only if

1. $\forall j$, $Z^{(j)}$ is a max-stable variable with norming constants $(a_{n,j}, b_{n,j})$
2. $Z^* := (-1/\log G_1(Z^{(1)}), \dots, -1/\log G_d(Z^{(d)}))$ is a simple max-stable vector.

The proof is left as an exercise.

Hint: For the direct implication, show that for $x \succ 0$, $\mathbb{P}(\bigvee_{i=1}^n Z_i^*/n \preceq x) = \mathbb{P}(Z_1^* \preceq x)$. The converse is similar.

A consequence of Proposition 3.2.2 is that it is enough to characterize simple max-stable vectors.

3.2.2 Angular Measure

If G is simple max-stable, we have $G^t(tx) = G(x)$ and the support of G is $[0, \infty]^d$. We thus take $E = [0, \infty]^d \setminus \{0\}$, and we have

$$G(x) = \begin{cases} e^{-\mu[0,x]^c} & \text{if } x \succeq 0 \\ 0 & \text{otherwise .} \end{cases}$$

From the homogeneity property of G we deduce that for $t > 0$,

$$\mu([0, tx]^c) = t^{-1}\mu[0, x]^c,$$

so that for any $A \in E$, measurable, $\mu(tA) = t^{-1}\mu(A)$.

Choose any norm $\|\cdot\|$ on \mathbb{R}^d and denote S_{d-1} the corresponding positive orthant of the unit sphere. Define a (finite) measure Φ on S_{d-1} :

$$\Phi(A) = \mu\{tA : t \geq 1\}.$$

Exercise 3.3:

Show that Φ is a finite measure.

Let T denote the polar coordinate transformation, that is

$$\begin{aligned} T : [0, \infty]^d \setminus \{0\} &\rightarrow (0, \infty) \times S_{d-1} \\ x &\mapsto (\|x\|, \frac{1}{\|x\|}x). \end{aligned}$$

Now the image measure of μ satisfies, for $r > 0$ and $A \subset S_{d-1}$,

$$\mu \circ T^{-1}[r, \infty] \times Ar^{-1}\Phi(A),$$

it is thus a product measure. In other words, if (R, W) is a random pair following the probability measure $\frac{\mu \circ T^{-1}}{\mu \circ T^{-1}[1, \infty] \times S_{d-1}}$, Then $R \perp\!\!\!\perp W$, $W \sim \text{Pareto}(1)$ and $W \sim \Phi(\cdot)/\Phi(S_{d-1})$. Notice that R is a ‘radius’ and W is an ‘angle’.

From a statistical point of view, this means that only the angular component of μ need to be estimated.

Recovering G from Φ Recall $G(x) = \exp\{-\mu[0, x]^c\}$. How to write G as a function of Φ ?

A change of variables and a call to Fubini show that

$$\mu[0, x]^c = \int_{S_{d-1}} \max_{j=1, \dots, d} \frac{w_j}{x_j} d\Phi(w).$$

Exercise 3.4:

Prove the latter display.

Thus, for $x \succeq 0$,

$$G(x) = e^{-\int_{S_{d-1}} \max_{j=1, \dots, d} \frac{w_j}{x_j} d\Phi(w)} \quad (3.9)$$

The choice of unit Fréchet margins implies that $G_j(1) = e^{-1}$. Writing (3.9) at $x = (0, \dots, 0, 1, 0, \dots)$, one obtains ‘first moment constraints’ of Φ ,

$$\forall j \leq d, \quad \int_{S_{d-1}} w_j d\Phi(w) = 1. \quad (3.10)$$

Exercise 3.5:

Show that conversely, any distribution function of the kind $G(x) = \exp\{-\mu[0, x]^c\}$ with $d\mu \circ T^{-1} = \frac{dr}{r^2}d\Phi$ where Φ is finite and satisfies (3.10) is simple max-stable.

We summarize the discussion:

Proposition 3.2.3 (Characterization of simple max-stable distributions)

Let G be a c.d.f. on \mathbb{R}^d , and let Y be a random vector distributed according to G . Define $E = [0, \infty]^d \setminus \{0\}$. The following are equivalent.

1. G is simple max-stable.
2. $\exists \mu$ a Radon measure on E verifying

$$\forall t > 0, \forall A \subset E \text{ measurable, } \mu(tA) = t^{-1}\mu(A) \tag{3.11}$$

$$\mu\{x \in E : x_j \geq 1\} = 1, \quad \forall j \in \{1, \dots, d\}. \tag{3.12}$$

such that

$$G(x) = \begin{cases} 0 & \text{if } x \notin E \\ \exp\{-\mu[0, x]^c\} & \text{if } x \in E \end{cases}$$

3. $\exists \Phi$ a finite measure on S_{d-1} satisfying the moment constraints (3.10) such that for $x \in \mathbb{R}^d$,

$$G(x) = \begin{cases} 0 & \text{if } x \notin E \\ \exp\left\{-\int_{S_{d-1}} \max_{j=1}^d \frac{w_j}{x_j} d\Phi(w)\right\} & \text{if } x \in E \end{cases}$$

4. \exists a Radon measure μ satisfying (3.11) and (3.12) and \exists a point process $N = \sum_{k \geq 1} \delta_{t_k, Z_k}$ with intensity measure $d\lambda = \frac{dt}{t^2} \otimes d\mu$ such that

$$Y = \bigvee_{k: t_k \leq 1} Z_k \bigvee 0.$$

5. $\exists \Phi$ a finite measure on S_d verifying (3.10) and $\exists \Gamma = \sum_{k \geq 0} \delta_{R_k, W_k}$ a Poisson process with intensity measure $\frac{dr}{r^2} \otimes d\Phi$ such that $Y \stackrel{d}{=} \bigvee_{k \geq 1} R_k W_k$.

Proof. The equivalence between (1), (2), (3) and (4) follows from the argument preceding the statement. The equivalence with statement (5) remains to be shown. We prove (3) \iff (5). ■

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We conclude this section with a series of exercises taken from Resnick (1987), chapter 5.4.

Exercise 3.6:

Give an example of one of each of the following

- A c.d.f. G which is max-id but not max-stable
- A max-stable distribution which has one marginal distribution degenerate
- A max-stable distribution which is not absolutely continuous with respect to the Lebesgue measure on \mathbb{R}^d .

(take $d = 2$ for simplicity)

Exercise 3.7:

On \mathbb{R}_+^3 , define $G(x, y, z) = \exp\{-\frac{1}{2}(x^{-1} \vee y^{-1} + x^{-1} \vee z^{-1} + y^{-1} \vee z^{-1})\}$. Check that G is simple max-stable. Pick a norm, and characterize the angular measure Φ associated with μ , where $G(x) = e^{-\mu[0,x]^c}$.

Exercise 3.8:

Same as Exercise 3.7 with $G(x, y, z) = \exp\{-\frac{1}{2}(\sqrt{x^{-2} + y^{-2}} + \sqrt{x^{-2} + z^{-2}} + \sqrt{y^{-2} + z^{-2}})\}$.

Exercise 3.9:

Consider $d = 2$ and the angular measure for the L_2 norm, $\Phi = \sqrt{2}\delta_{(1/\sqrt{2}, 1/\sqrt{2})}$. Give the expression of the simple max-stable c.d.f. G associated with Φ .

3.3 Maximum domain of attraction and Peaks-Over-Threshold: the multivariate case

As in the 1D case, the MDA condition may be reformulated in terms of Peaks-Over-Threshold conditions. A preliminary step is standardization. Then the 1D definition of regular variation can be extended and an interpretation in terms of point process convergence is possible.

3.3.1 Standardization in a max-domain of attraction

Idea: the multivariate MDA condition for a random vector X is equivalent to

1. MDA conditions on every component $X^{(j)}$
2. A standard MDA condition on the standardized variable

$$X^* = (-1/\log F_1(X^{(1)}), \dots, -1/\log F_d(X^{(d)})),$$

which writes $\frac{1}{n} \bigvee_{i=1}^n X_i^* \xrightarrow{w} Z^*$, where Z^* is a simple max-stable random vector.

Proposition 3.3.1

Let $X, X_i, i = 1, \dots, n \stackrel{\text{i.i.d.}}{\sim} F$. Assume that the marginal distributions F_j are continuous. Define for $i \geq 1$,

$$X_i^* = \left(\frac{1}{1 - F_1(X_{i,1})}, \dots, \frac{1}{1 - F_d(X_{i,d})} \right).$$

Let G be a non-degenerate max-stable d.f. and let $Y \sim G$. The following statements are equivalent.

1. $\exists (a_n)_{n \geq 0} \in (\mathbb{R}_+^*)^d, \exists (b_n)_{n \geq 0} \in \mathbb{R}^d : \frac{\bigvee_{i=1}^n X_i - b_n}{a_n} \xrightarrow{w} Y$
2. Marginal and joint weak convergence both occur:

$$\left\{ \begin{array}{l} \forall j \in \{1, \dots, d\}, \frac{\bigvee_{i=1}^n X_{i,j} - b_{n,j}}{a_{n,j}} \xrightarrow{w} Y_j \sim G_j, \\ \frac{1}{n} \bigvee_{i=1}^n X_i^* \xrightarrow{w} Y^* := \left(\frac{-1}{\log G_1(Y_1)}, \dots, \frac{-1}{\log G_d(Y_d)} \right) \end{array} \right.$$

Proof. We show that 1. \Rightarrow 2., the proof of the converse statement is similar.

Assume 1. Then marginal convergence is immediate (joint weak convergence implies marginal weak convergence). We need to prove the weak convergence of the standardized maxima. It is enough to show that

$$\mathbb{P}^n(X^* \prec nx) \xrightarrow{w} \mathbb{P}(Y^* \prec x).$$

For $x \in \mathcal{C}(Y^*)$, we have, denoting $U_j(p) = F_j^{\leftarrow}(1 - 1/p)$.

$$\begin{aligned} \mathbb{P}^n(X^* \prec nx) &= \mathbb{P}\left(F_j(X_j) < 1 - \frac{1}{nx_j}, j = 1, \dots, d\right)^n \\ &= \mathbb{P}\left(X_j < F_j^{\leftarrow}\left(1 - \frac{1}{nx_j}\right), j = 1, \dots, d\right)^n \\ &= \mathbb{P}\left(\frac{X_j - b_{n,j}}{a_{n,j}} < \frac{U_j(nx_j) - b_{n,j}}{a_{n,j}}, j = 1, \dots, d\right)^n \end{aligned}$$

Now, the function $x \mapsto \frac{U_j(nx_j) - b_{n,j}}{a_{n,j}}$ is the generalized inverse of $x \mapsto 1/(n(1 - F_j(a_{n,j}x + b_{n,j})))$. The latter expression is equivalent, for fixed x as $n \rightarrow \infty$, to $-1/\log(F_j^n(a_{n,j}x + b_{n,j}))$ which converges weakly to $-1/\log G_j(x_j)$ by continuous mapping. Lemma 1.2.4 (weak convergence of the inverse) thus implies that $\frac{U_j(nx_j) - b_{n,j}}{a_{n,j}} \xrightarrow{w} (-1/\log(G_j(x)))^{\leftarrow} = G_j^{\leftarrow}(e^{-1/x})$. By continuity, we obtain that

$$\begin{aligned} \mathbb{P}^n(X^* \prec nx) &\sim_{n \rightarrow \infty} \mathbb{P}\left(\frac{X_j - b_{n,j}}{a_{n,j}} < G_j^{\leftarrow}(e^{-1/x_j}), j = 1, \dots, d\right)^n \\ &\xrightarrow[n \rightarrow \infty]{} G(G_1^{\leftarrow}(e^{-1/x_1}), \dots, G_1^{\leftarrow}(e^{-1/x_1})) \\ &= \mathbb{P}(G_j(Y_j) < e^{-1/x_j}, j = 1, \dots, d) \\ &= \mathbb{P}(Y^* \prec x). \end{aligned}$$

■

Proposition 3.3.1 tells us that we may restrict ourselves to the max-domain of attraction of simple max-stable vectors, *i.e.* consider random vectors $X^* \in \mathbb{R}^d$ such that

$$\frac{1}{n} \bigvee_{i=1}^n X_i^* \xrightarrow{w} Y^* \tag{3.13}$$

where Y^* is simple max-stable with distribution $G^*(x) = e^{-\mu[0,x]^x}$, $x \succ 0$. We shall see in the next paragraphs that this condition is equivalent to the weak convergence of properly normalized excesses above large multivariate thresholds, and also to a condition on the cdf of X^* which is a multivariate generalization of the Regular variation condition (2.14) introduced in Chapter 2.

3.3.2 Convergence of multivariate Peaks-over-Threshold

Let us rephrase the standard MDA condition (3.13): we have

$$\begin{aligned}
(3.13) \quad & \iff F^*(nx) \xrightarrow[n \rightarrow \infty]{} G^*(x), \quad x \succ 0 \\
& \iff n \log[1 - (1 - F^*(nx))] \xrightarrow[n \rightarrow \infty]{} \log G^*(x), \quad x \succ 0 \\
& \iff n(1 - F^*(nx)) \xrightarrow[n \rightarrow \infty]{} -\log G^*(x) = \mu[0, x]^c, \quad x \succ 0 \\
& \iff n\mathbb{P}\left(n^{-1}X^* \in [0, x]^c\right) \xrightarrow[n \rightarrow \infty]{} \mu[0, x]^c \\
& \iff t\mathbb{P}\left(t^{-1}X^* \in [0, x]^c\right) \xrightarrow[t \rightarrow \infty, t \in \mathbb{R}]{} \mu[0, x]^c
\end{aligned} \tag{3.14}$$

where the last equivalence is obtained by monotonicity of F^* . The same argument as in the proof of Proposition 3.1.7 shows that the above condition implies that the measures $\mu_t(\cdot) = t\mathbb{P}(t^{-1}X^* \in \cdot)$ converge vaguely to μ , and the converse implication is immediate. Another consequence is that μ characterizes the distribution of X ‘far from the origin’. Indeed consider the conditional distribution $P_t(A) = \mathbb{P}(X^* \in tA \mid \|X^*\| > t)$ defined on $\Omega^c = \{x : \|x\| \geq 1\}$. Under the standard MDA condition, we have

$$\begin{aligned}
P_t(A) &= \frac{\mathbb{P}(X^* \in tA)}{\mathbb{P}(\|X^*\| > t)} \\
&= \frac{t\mathbb{P}(X^* \in tA)}{t\mathbb{P}(\|X^*\| > t)} \\
&\xrightarrow[t \rightarrow \infty]{\frac{\mu(A)}{\mu(\Omega^c)}} \frac{1}{Z} \mu(A)
\end{aligned}$$

with $Z = \mu(\Omega^c)$ a normalizing constant. We summarize the discussion and leave the proofs of the remaining equivalences to the reader.

Proposition 3.3.2

Let $X = (X_1, \dots, X_d)$ be a random vector with distribution F with marginal distributions $F_j, j \leq d$, and let Y be a random vector with simple max-stable cdf $G^*(x) = e^{-\mu[0, x]^c}$ on $E = [0, \infty]^d \setminus \{0\}$ and angular measure $\Phi(B) = \mu\{tW, t \geq 1, w \in B\}$, for $B \subset S_{d-1}$, measurable. The following conditions are equivalent

1. $F^n(nx) \xrightarrow[n \rightarrow \infty]{} G^*(x), \quad x \succ 0.$
2. $\frac{1}{n} \bigvee_{i \leq n} X_i \xrightarrow{w} Y.$
3. $\mu_t(\cdot) = t\mathbb{P}(t^{-1}X \in \cdot) \xrightarrow{v} \mu$ on $E.$
4. $F_1^n(nx_1) \xrightarrow[n \rightarrow \infty]{} e^{-1/x_1}, \quad x_1 > 0$ and on the space $E,$

$$\mathbb{P}\left(t^{-1}X \in \cdot \mid \|X\| > t\right) \xrightarrow{v} \frac{\mu(\cdot)}{\mu(\Omega^c)}.$$

5. $F_1^n(nx_1) \xrightarrow[n \rightarrow \infty]{} e^{-1/x_1}, \quad x_1 > 0$ and letting $R = \|X\|$ and $W = \|X\|^{-1}X$, for $B \subset S_{d-1}$ and $r \geq 1,$

$$\mathbb{P}(W \in B, R > tr \mid R > t) \xrightarrow[t \rightarrow \infty]{} \frac{1}{r} \frac{\Phi(B)}{\Phi(S_{d-1})}.$$

Exercise 3.10:

Show that (4.) implies (3.) in Proposition 3.3.2.

3.3.3 Multivariate regular variation

Definition 3.3.3 (Multivariate RV of functions). Let $E = [0, \infty]^d \setminus \{0\}$ and $U : E \rightarrow \mathbb{R}_+$ a real valued function of d variables. U is called multivariate regularly varying if denoting by $\mathbf{1}$ the constant vector $(1, \dots, 1) \in \mathbb{R}^d$, there exists a function $\lambda : E \rightarrow \mathbb{R}^+$ such that for all $x \in E$,

$$\frac{U(tx)}{Ut\mathbf{1}} \xrightarrow[t \rightarrow \infty]{} \lambda(x)$$

Proposition 3.3.4

Let λ be a limit function in the setting of Definition 3.3.3. Then $\exists \rho \in \mathbb{R}$ such that λ is ρ -homogeneous, i.e. for $x \in E$ and $s > 0$,

$$\lambda(sx) = s^\rho \lambda(x).$$

Exercise 3.11:

Prove Proposition 3.3.4.

hint: prove the statement for fixed x then show that the RV index $\rho(x)$ does not depend on x .

If U is a multivariate RV function which limit function λ has homogeneity index ρ , then U is said to be regularly varying with index ρ and we denote $U \in RV(\rho)$.

Proposition 3.3.5 (Equivalent characterization of $RV(\rho)$)

A function $U : E \rightarrow \mathbb{R}_+$ is $RV(\rho)$ for some $\rho \in \mathbb{R}$ iff. There exists a function $V : \mathbb{R}_+^* \rightarrow \mathbb{R}_+^* \in RV(\rho)$ (in the univariate sense) and a limit function $\tilde{\lambda} : E \rightarrow \mathbb{R}_+$ such that for $x \in E$,

$$\frac{1}{V(t)} U(tx) \xrightarrow[t \rightarrow \infty]{} \tilde{\lambda}(x)$$

Exercise 3.12:

Prove Proposition 3.3.5.

In a probabilistic context, the considered RV function are the tail distributions of random variables.

Definition 3.3.6 (multivariate RV tails). A c.d.f. F in \mathbb{R}_+^d has multivariate regularly varying tail if $1 - F$ is a multivariate RV function in the sense of Definition 3.3.3.

The relationships between multivariate POT, vague convergence of tail measures and tail regular variation is summarized in the next proposition (See Resnick (2007), Th. 6.1)

Proposition 3.3.7 (Tail multivariate regular variation and vague convergence of measures) Let $E = [0, \infty]^d \setminus \{0\}$ and let $X \sim F$ a random vector valued in \mathbb{R}_+^d . Let $\alpha > 0$. The following are equivalent

1. $1 - F \in RV(-\alpha)$.

2. $\exists (a_n)_n \rightarrow \infty$ and $\exists \nu \in \mathcal{M}(E)$ such that

$$n\mathbb{P}(a_n^{-1}X \in \cdot) \xrightarrow{v} \nu$$

where ν is a homogeneous measure with index $-\alpha$, i.e. $\nu(tA) = t^{-\alpha}\nu(A)$, for $t > 0$ and $A \subset E$, measurable.

3. There exist H a probability measure on the sphere S_{d-1} , a constant $c > 0$, and a sequence $a_n \rightarrow \infty$ such that letting $R = \|X\|$ and $W = X/R$,

$$n\mathbb{P}((R/a_n, W) \in \cdot) \xrightarrow{v} c\nu_\alpha \otimes H$$

in $\mathcal{M}((0, \infty] \times S_{d-1})$, where $\nu_\alpha[x, \infty] = x^{-\alpha}$, $x > 0$.

Exercise 3.13 (A simple question):

Considering a random pair $X = (X_1, X_2)$ (ex: asset returns/ river flows / temperatures at two locations) such that X_1 and X_2 are likely to take extreme values simultaneously. The general goal is to quantify the strength of their association. To be more precise, the question is: how to estimate the probability that the second components is very large, given that the first component is very large?

In this exercise this vague question is rephrased in such a way that we may answer easily. Assume that X satisfies (3.2) for some limit G . In order to be able to apply the framework of (standard) multivariate regular variation, let $V = (V_1, V_2)$ with $V_j = 1/(1 - F_j(X_j))$ where F_j is the marginal cdf of X_j .

1. Download the dataset 'data.txt' from the website (e.g. through the command `read.table("data.txt")` in R).
2. write a function `ranktransformer` which transforms the dataset $(X_i, i \leq n)$ into $\hat{V}_i, i \leq n$ where $\hat{V}_{i,j}$ is obtained as an empirical version of $V_{i,j}$, i.e. using an empirical estimate of F_j instead of F_j . In order to avoid division by zero, it is recommended to use

$$\hat{F}_j(x) = \frac{1}{n+1} \sum_{i \leq n} \mathbb{1}\{X_{i,j} \leq x\}$$

3. Prove (theoretically) that as $t \rightarrow \infty$, and for any fixed $\lambda > 0$, the quantity

$$p_t(\lambda) = \mathbb{P}(V_2 > \lambda t \mid V_1 > t)$$

converges to some limit $p_\infty(\lambda)$. Express $p(\lambda)$ as a function of the limit measure μ in Equation (3.14). You may of course use the results from the course.

In the sequel the goal is to estimate $p_\infty(\lambda)$ for some fixed values of λ , say $\lambda = 1$ or $\lambda = 2$.

4. Propose an empirical estimator $\hat{p}_k(\lambda)$ of $p_\infty(\lambda)$ based on its subasymptotic version $p_t(\lambda)$ and the data $X_i, i \leq n$, where t is taken as the k^{th} order statistic (with $k \ll n$) of the marginal dataset $\hat{V}_{i,1}, i \leq n$

5. Implement the estimator as a function taking as arguments (Data, krange, Lambda) where krange is a vector of values of k for which the estimator must be computed. The function should return a vector of probabilities of same length as krange.
6. Let $\lambda = 2$. Based on plots of the quantities $\hat{p}_k(\lambda)$ as a function of k , propose a reasonable range of values k in order to estimate $p_\infty(\lambda)$. Give a final estimate and a an order of magnitude of its variability (as k varies within your 'reasonable' range).

Appendix A

Technicalities for Chapter 1

A.1 Monotone functions: additional results

Lemma A.1.1 (local uniform convergence of monotone functions)

Let $(H_n)_{n \in \mathbb{N}}$ and H be monotone functions $\mathbb{R} \rightarrow [-\infty, \infty]$, such that $H_n \xrightarrow{w} H$. If H is continuous on an interval $I \subset \mathbb{R}$ (in particular H has to be finite on I), then the convergence is locally uniform on I , i.e. for $a < b \in I$,

$$\sup_{x \in [a, b]} |H_n(x) - H(x)| \xrightarrow{n \rightarrow \infty} 0.$$

Sketch of proof. Since H is uniformly continuous on $[a, b]$; For $\epsilon > 0$, there is a subdivision $a = x_0 < x_1 < \dots < x_K = b$; such that the variations of H are less than ϵ on each $[x_i, x_{i+1}]$. Use pointwise convergence on the finite set (x_0, \dots, x_k) and monotonicity to conclude. ■

A.2 Proof of Lemma 1.2.5 (Weak convergence of the inverse)

Weak convergence implies weak convergence of the inverse

We assume that $H_n \xrightarrow{w} H$, and we show that $H_n^{\leftarrow} \xrightarrow{w} H^{\leftarrow}$. Let $y \in \mathcal{C}(H^{\leftarrow})$. In particular $H^{\leftarrow}(y)$ is finite. Let $\epsilon > 0$. Since the discontinuity points of a monotone functions are at most countable, there exists $x \in \mathcal{C}(H)$ such that $H^{\leftarrow}(y) - \epsilon < x < H^{\leftarrow}(y)$. Then, from Lemma 1.2.4, $H(x) < y$. Since for such an x , $H_n(x) \xrightarrow{n \rightarrow \infty} H(x)$, we have for n large enough, $H_n(x) < y$ as well, so that, from Lemma 1.2.4 again, $x < H_n^{\leftarrow}(y)$. Thus, $\exists n_0$ such that for $n \geq n_0$, $H^{\leftarrow}(y) - \epsilon < x < H_n^{\leftarrow}(y)$. Since ϵ is arbitrary,

$$\liminf H_n^{\leftarrow}(y) \geq H^{\leftarrow}(y).$$

An upper bound on $\limsup H_n^{\leftarrow}(y)$ is obtained similarly: Since $y \in \mathcal{C}(H^{\leftarrow})$, we may choose $t > y$ such that $H^{\leftarrow}(t) \leq H^{\leftarrow}(y) + \epsilon$. Also, we may pick x' in $(H^{\leftarrow}(t), H^{\leftarrow}(t) + \epsilon) \cap \mathcal{C}(H)$. For such x' , Lemma 1.2.4 implies

$$H(x') \geq t > y$$

Thus, for some n_1 and for all $n \geq n_1$, $H_n(x') \geq y$ as well, and using from Lemma 1.2.4 again, for such n ,

$$H_n^{\leftarrow}(y) \leq x' \leq H_n^{\leftarrow}(y) + 2\epsilon.$$

Thus

$$\limsup H_n^{\leftarrow}(y) \leq H^{\leftarrow}(y),$$

and the proof is complete.

Converse statement

Let us assume that

$$H_n^{\leftarrow} \xrightarrow{w} H^{\leftarrow} \quad \text{as } n \rightarrow \infty.$$

and that conditions (i) and (ii) from Lemma 1.2.5 are satisfied. Let $x \in \mathcal{C}(H)$ (in particular, $H(x)$ is finite) and $\epsilon > 0$. We need to show that for n large enough (say $n \geq n_0$),

$$H_n(x) \leq H(x) + \epsilon, \tag{A.1}$$

$$\text{and } H_n(x) \geq H(x) - \epsilon \tag{A.2}$$

We first show (A.1). By hypothesis (ii), $\exists x' > x : H(x) < H(x') < \sup_{t: H(t) < \infty} H(t)$. Thus H^{\leftarrow} is finite on the open interval $(H(x), H(x'))$. The number of discontinuity points of H^{\leftarrow} on this interval is at most countable, thus $\exists y \in \mathcal{C}(H^{\leftarrow}) : H(x) < y < H(x) + \epsilon$. Using Lemma 1.2.4, we obtain $x < H^{\leftarrow}(y)$. Weak convergence of H_n^{\leftarrow} then implies that for n large enough, $x < H_n^{\leftarrow}(y)$ as well. Thus $H_n(x) < y < H(x) + \epsilon$, which proves (A.1).

For the proof of (A.2), we need to distinguish between the cases $H(x) > \inf_{\mathbb{R}} H$ and $H(x) = \inf_{\mathbb{R}} H$.

Case 1: $H(x) > \inf_{\mathbb{R}} H$. By continuity of H at x , we may choose $t < x$ such that $H(t) > \max(H(x) - \epsilon/2, \inf_{\mathbb{R}} H)$. Then H^{\leftarrow} is finite on $(\inf_{\mathbb{R}} H, H(t))$, and again, admits only a countable number of discontinuity on this interval. Let then $y' \in \mathcal{C}(H^{\leftarrow})$ such that $H(t) - \epsilon/2 < y' < H(t)$. Lemma 1.2.4 again ensures that $H^{\leftarrow}(y') \leq t < x$, so that for n large enough, $H_n^{\leftarrow}(y') \leq x$ as well, whence $H_n(x) \geq y' > H(t) - \epsilon/2 > H(x) - \epsilon$ and (A.2) is true.

Case 2: $H(x) = \inf_{\mathbb{R}} H$. Since $x \in \mathcal{C}(H)$, necessarily $H(x) = \inf_{\mathbb{R}} H$ is finite, and hypothesis (i) ensures that for all $n \in \mathbb{N}$, $H_n(x) \geq H(x)$ so that (A.2) is immediate.

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